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LIGO Scientific Collaboration

Virgo Collaboration

KAGRA Collaboration

Tiffany Z. Summerscales

Andrews University, tzs@andrews.edu

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All-sky search for long-duration gravitational-wave bursts in the third Advanced LIGO and Advanced Virgo run

LIGO Scientific Collaboration, Virgo Collaboration, and KAGRA Collaboration
(compiled July 30, 2021)

After the detection of gravitational waves from compact binary coalescences, the search for transient gravitational-wave signals with less well-defined waveforms for which matched filtering is not well-suited is one of the frontiers for gravitational-wave astronomy. Broadly classified into “short” $\lesssim 1$ s and “long” $\gtrsim 1$ s duration signals, these signals are expected from a variety of astrophysical processes, including non-axisymmetric deformations in magnetars or eccentric binary black hole coalescences. In this work, we present a search for long-duration gravitational-wave transients from Advanced LIGO and Advanced Virgo’s third observing run from April 2019 to March 2020. For this search, we use minimal assumptions for the sky location, event time, waveform morphology, and duration of the source. The search covers the range of 2 – 500 s in duration and a frequency band of 24 – 2048 Hz. We find no significant triggers within this parameter space; we report sensitivity limits on the signal strength of gravitational waves characterized by the root-sum-square amplitude h_{rss} as a function of waveform morphology. These h_{rss} limits improve upon the results from the second observing run by an average factor of 1.8.

I. INTRODUCTION

The third observing run of the Advanced LIGO [1] and Advanced Virgo [2] detectors has revealed a large number of new gravitational-wave signals from the collision of compact objects. Many binary black hole systems [3] have been identified. These include GW190521 [4] with the largest progenitor masses discovered so far, and GW190814, a merger containing an object in the “mass-gap” between neutron stars and black holes [5]. A second binary neutron star (BNS) system was also discovered, GW190425 [6], following the first BNS system GW170817 [7], which also produced GRB 170817A [8] and an optical transient, AT 2017gfo [9]. In addition, two neutron star-black hole (NSBH) binary coalescences (GW200105.162426 and GW200115.042309) have been finally detected [10].

Searches for “long” $\gtrsim 1$ s duration signals cover a variety of astrophysical phenomena [11]. While well-modeled compact binary coalescences can have similar durations in the sensitive band of the interferometers and the methods employed in this paper are also sensitive to them, this search is not aimed at these systems as matched filtering is much more sensitive. However, there are less well-defined waveforms for which matched filtering is not well-suited. Plausible processes include fallback accretion onto a rapidly rotating black hole [12] or in newborn neutron stars [13–15]. They also include non-axisymmetric deformations in magnetars [16] or accretion disk instabilities and fragmentation of material spiraling into a black hole [17–19] and in the central engine of super-luminous supernovae [20, 21]. Figure 1 shows several different realizations of the corresponding waveform morphologies.

In this paper, we present the results of unmodeled long-duration transient searches from the third observing run, updating the results from the first two observing runs [22, 23]. As in previous analyses [22–25], three pipelines are used; their different assumptions and data handling techniques yield complementary coverage of the

signal models.

The paper is organized as follows. The data used in the analysis is described in Section II. The algorithms used to analyze the data are outlined in Section III. The results of the analysis and their implications are discussed in Section IV.

II. DATA

The third observing run (O3) of Advanced LIGO and Advanced Virgo spanned April 1, 2019 - March 27, 2020. O3 was broken up into two segments, with O3a running April 1, 2019 - Oct 1, 2019 and O3b running November 1, 2019 - March 27, 2020; together, these correspond to 330 days. It is customary to assess detector sensitivities in terms of a binary neutron star inspiral range (BNS range), which is the average distance to which these signals could be detected [26, 27]. Detector upgrades to the LIGO detectors in Hanford, WA and Livingston, LA yielded binary neutron star ranges of ~ 115 Mpc and 133 Mpc respectively, amounting to improvements of $\sim 50\%$ with respect to O2. Similarly, Advanced Virgo reached a binary neutron star range of ~ 50 Mpc, a $\sim 100\%$ improvement. In the following, the algorithms employed require at least two detectors to be available to process the data; therefore, only data where both LIGO detectors are simultaneously available is used. Due to the significant difference in detector alignment and sensitivities, the Virgo data in the analysis would not improve the coincidence selection when the other two detectors are active, while the high rate of non-Gaussian noise would increase the overall false-alarm rate. We plan to include Virgo in the analysis of the next observing run.

A major challenge in searches for gravitational-wave transients is non-Gaussian noise. Known sources of noise, including non-linear sources such as time-varying spectral lines, from, e.g., machinery on-site, side-bands from the 60 Hz power lines, and time-varying spectral lines, can

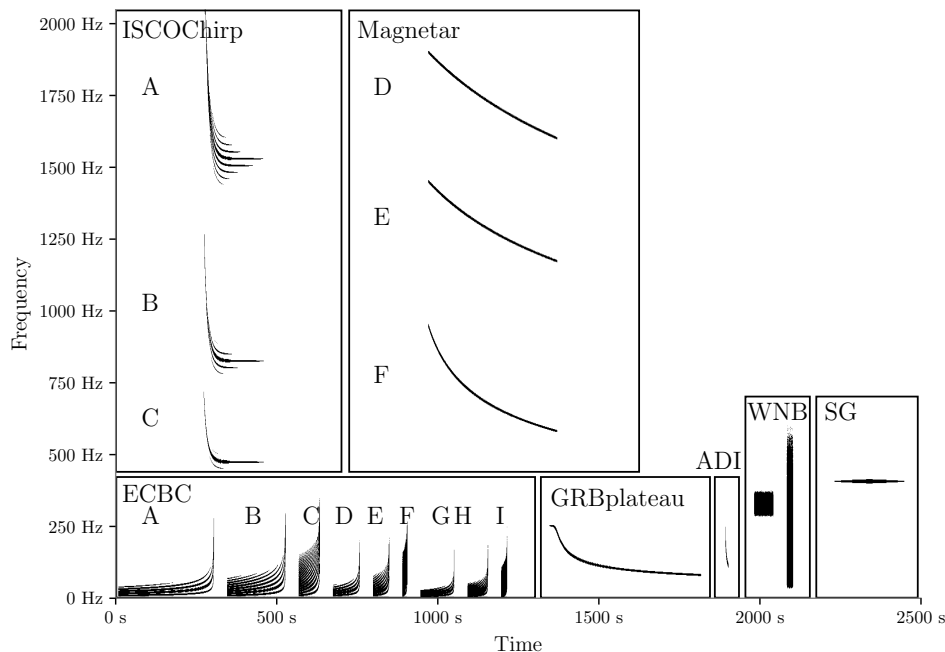


FIG. 1. Time-frequency spectrogram of the reference waveforms used in this search. The ISCOChirp waveforms have been shifted up in frequency by 50 Hz for readability. Durations range from 6 s (ADI-B) to 470 s (GRBplateau).

be witnessed and subtracted using both linear Wiener filters [28] and machine learning techniques [29, 30]. The analyses that follow use data for which some of the identified sources of noise that couple in linearly to the detector have been subtracted. Beyond spectral features, there are transient noise triggers known as *glitches*, which have a variety of origins [31]. Glitch rejection procedures rely on correlations with auxiliary channels [32, 33]; yet, noise transients not witnessed by auxiliary sensors remain and reduce sensitivity of the searches [34, 35]. Each pipeline, described in the next section, implements different strategies to reduce the impact from glitches. Altogether, during the third observing run, coincident data of sufficient quality to be analyzed totaled 204.4 days. Since some time segments are too short to be processed by search pipelines, a small fraction ($< 2\%$) of this coincident data is not analyzed.

III. SEARCHES

Long-duration unmodeled searches are now briefly reviewed, and we refer the reader to previous publications for further detail [22, 23]. Most unmodeled searches use time-frequency spectrograms with statistics derived from Fourier transforms or wavelet analysis performed on consecutive time segments. Pattern-recognition algorithms then are employed to search for gravitational waves in these spectrograms. These algorithms can be classified as: “seed-based” [36, 37], for which pixels above pre-determined thresholds are clustered, and

“seedless” [38, 39], for which sequences of pixels are derived from generic models, such as Bézier curves [38–42]. Seedless clustering algorithms are sensitive to narrow-band signals at the price of sensitivity to broadband sources, while seed-based algorithms are generally more sensitive to more generic waveform morphologies. These algorithms identify candidate gravitational-wave events known as *triggers*. To estimate the background, all pipelines use “time-slides,” [43, 44], where detector data is shifted by non-physical time delays and reanalyzed; this procedure is repeated a sufficient number of times such that at least 50 years of coincident live time is analyzed, allowing for a false alarm rate of 1 per 50 years to be estimated.

Three pipelines are deployed in the analysis: two different versions of the Stochastic Transient Analysis Multi-detector Pipeline - all sky (STAMP-AS) pipeline [11, 37, 42] and the long-duration configuration of coherent WaveBurst (cWB) [45]. The cWB pipeline is seed-based while the two STAMP-AS algorithms, Zebragard and Lonetrack, use seed-based and seedless clustering algorithms respectively. Altogether, the analyses are sensitive to transients lasting 2 – 500 s and covering a frequency band of 24 – 2048 Hz. Due to the short duration of binary black hole signals and the weakness of the coalescences containing neutron stars observed during O3 [6], we are not sensitive to and therefore do not excise any time around known compact binary coalescences. All false alarm rates reported are per pipeline, with no combination of searches made outside of reporting the most sensitive limit across the parameter space below.

STAMP-AS. Spectrograms, with duration 500 s and frequency band 24 – 2048 Hz and a pixel size of 1 s $\times$ 1 Hz, are derived with cross-power SNR as the statistic computed in the maps. Non-stationary, high-amplitude spectral features are masked to limit their effect on the search. Zebragard uses cuts on the fraction of SNR per time bin (summing all pixels of the same time index) and the ratio in SNR between detectors to remove data transients [22]; Lonetrack does not require this cut due to the narrowband assumption. During a short period of time, a time segment veto that flags periods of instabilities in the high-power laser at Hanford is applied on Zebragard triggers [35].

cWB. The algorithm used by cWB [45] is based on a maximum likelihood approach applied to the multiresolution time-frequency representation of the time series of the detectors’ data. Candidate triggers are identified as a cluster if there is a coherent excess power in the time-frequency pixel representation over the network data. The search is performed in the frequency range 24 – 2048 Hz. Selection criteria are applied on the duration and on the coherence of the trigger; the coherence coefficient, measuring the degree of correlation between the detectors, must be larger than 0.6 [45]. Moreover, the trigger energy-weighted duration, defined as

$$d = \sqrt{\frac{\sum w_i (t - t^*)^2}{\sum w_i}},$$

where t is the central time of the pixel, w the energy of the pixel, t^* the mean time and the sum is computed over the selected pixels of the event in all the resolutions, is required to be greater than 1.5 s. Since observed glitch excess in the 16 – 48 Hz band, associated with elevated anthropogenic noise, is different between the first and second part of the run, the acceptance criteria in the latter one have been slightly modified. The triggers have an energy-weighted duration larger than 0.5 s and a total duration greater than 5 s, this to ensure increased acceptance for the eccentric compact binary waveforms family discussed in the next section.

IV. RESULTS AND FUTURE PROSPECTS

The detection threshold is defined to be a false alarm rate lower than 1/50 years (equivalent to 6.3×10^{-10} Hz). None of the pipelines found triggers consistent with such a false alarm rate; the most significant triggers, non-overlapping between the different pipelines and consistent with the background, are listed in Table I. The most significant event reported by the cWB algorithm (statistical significance $\sim 1.7 \sigma$, p-value 0.088) shows a time-frequency map composed of two separated excess power cluster pixels, respectively, at 838 Hz and 861 Hz mean frequency. This trigger appears to be associated with a random (time) coincidence of pixels belonging to two different non-stationary spectral lines of unknown origin, at

Pipeline	FAR [Hz]	p-value	Frequency [Hz]	Duration [s]	Time [GPS]
cWB	1.0×10^{-8}	0.088	838-861	16	1252808855
Zebragard	5.6×10^{-8}	0.40	1650-1769	21	1244819393
Lonetrack	1.7×10^{-8}	0.14	1510-1937	417	1253105020

TABLE I. Properties of the most significant coincident triggers found by each of the long-duration transient search pipelines during the third observing run. FAR stands for false alarm rate, while the p-value is the probability of observing at least 1 noise trigger at higher significance than the most significant coincident trigger.

838 Hz (present in H1 and L1) and 861 Hz (present in H1). The STAMP-AS Zebragard and Lonetrack pipeline triggers are consistent with typical events identified in the background.

To place these results in context, upper limits are derived on the gravitational-wave strain amplitude using a set of simulated waveforms added coherently into detector data. Waveforms that span the parameter space in both frequency and time, as well as a sampling of potential astrophysical models, are used. For the astrophysical models, post-merger magnetars (Magnetar) [46], black hole accretion disk instabilities (ADI) [18], newly formed magnetar powering a gamma-ray burst plateau (GRBplateau) [16], eccentric inspiral-merger-ringdown compact binary coalescence waveforms (ECBC) [47], and broadband chirps from innermost stable circular orbit waves around rotating black holes (ISCOchirp) [12] are used (see Ref. [48] for further developments). To fill out the parameter space, “ad-hoc” waveforms, band-limited white noise burst (WNB) and sine-Gaussian bursts (SG) are also used. Their time-frequency spectrograms are shown in Figure 1.

The upper limits on the gravitational-wave strain amplitude are typically reported for unmodeled searches using the root-sum-square gravitational-wave amplitude at the Earth, h_{rss} ,

$$h_{\text{rss}} = \sqrt{\int_{-\infty}^{\infty} (h_+^2(t) + h_\times^2(t)) dt}, \quad (1)$$

where h_+ and $h_\times$ are the two non-whitened signal polarizations. Simulations are varied with h_{rss} and injected uniformly in time, sky location, polarization angle and the cosine of the inclination angle of the assumed source.

Upper limits on gravitational-wave strain versus mean frequency for sources detected with 50% efficiency and a false alarm rate of 1 event in 50 years are shown in Figure 2. The strongest bounds obtained from the three pipelines are shown on the plot. Because each pipeline uses a different clustering algorithm, their relative sensitivities vary with waveform morphology. Lonetrack, which uses seedless clustering, performs best on magnetar signals (Magnetar and GRBplateau) but is not sensitive to white noise bursts. Zebragard and Coherent

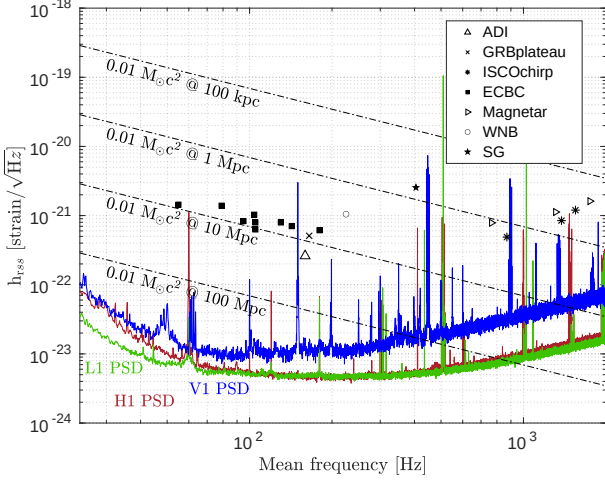


FIG. 2. The GW root-sum-square strain amplitude versus mean frequency at 50% detection efficiency and a FAR of 1/50 years. The red, green and blue curves are the averaged amplitude spectral noise densities for Hanford, Livingston and Virgo detectors to show that the search results follow the detectors' sensitivity frequency. We also show in dashed-dotted lines the energy of fractions of $0.01 M_{\odot} c^2$, with examples at 100 kpc, 1 Mpc, 10 Mpc and 100 Mpc shown.

WaveBurst give the most constraining values with similar sensitivities for most of the remaining waveforms. On average, for all waveforms considered in this paper, the h_{rss} sensitivity improved by a factor of 1.8 upon the analysis from the second observing run [23].

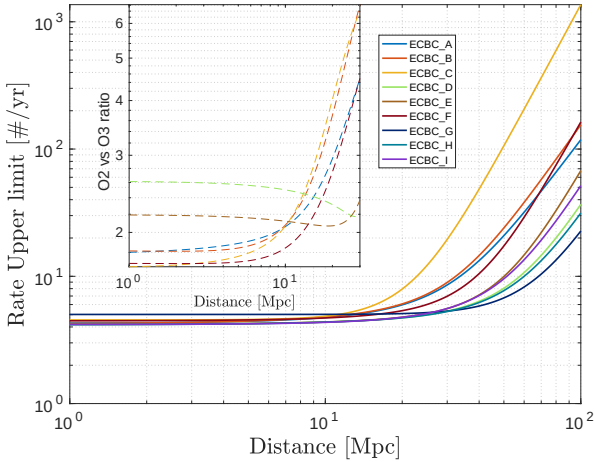


FIG. 3. Upper limits at 90% confidence level on the rate of eccentric compact binary coalescences as a function of the distance. Only the best result is shown for each waveform. The inset shows the ratio of the rates with respect to O2 results [23] for ECBC_A to ECBC_F (see Table II for parameters).

For the eccentric binary waveforms, we determine 90% confidence level limits on the rate of events. We do this

Waveform	$M_1 [M_{\odot}]$	$M_2 [M_{\odot}]$	e	$\mathcal{R}_{90\%} [\text{Gpc}^{-3} \text{yr}^{-1}]$
ECBC_A	1.4	1.4	0.2	9.97×10^2
ECBC_B	1.4	1.4	0.4	8.09×10^2
ECBC_C	1.4	1.4	0.6	3.21×10^3
ECBC_D	3.0	3.0	0.2	3.99×10^2
ECBC_E	3.0	3.0	0.4	8.89×10^2
ECBC_F	3.0	3.0	0.6	2.43×10^3
ECBC_G	5.0	5.0	0.2	1.50×10^3
ECBC_H	5.0	5.0	0.4	5.10×10^2
ECBC_I	5.0	5.0	0.6	6.98×10^2

TABLE II. Rate upper limits per unit volume at 90% confidence level on eccentric compact binary coalescences with various masses and eccentricity e , computed with equation 2.

using the loudest event statistic method [49]. Taking as an example the eccentric binary waveforms, the 90% upper limits on the event rates as a function of distance are highlighted in Figure 3. In addition, Table II gives the upper limits $\mathcal{R}_{90\%}$ at 90% confidence on the rate of eccentric binary coalescences per unit volume. Following [50], and assuming an isotropic and uniform distribution of sources, $\mathcal{R}_{90\%}$ is given by

$$\mathcal{R}_{90\%} = \frac{2.3}{4\pi T \int_0^{r_{\text{max}}} dr r^2 \epsilon(r)}, \quad (2)$$

where $\epsilon(r)$ is the detection efficiency as a function of distance, computed as the fraction of transients detectable at a given distance [50], r_{max} is the maximum detectable distance, and $T = 204.4$ days is the total observing time. For 1.4 – 1.4 solar masses eccentric binaries, rate upper limits are $\sim 1.5 - 2$ lower than the ones computed in [51] for O2 data. Such improvement can be explained by both the increased sensitivity of the search and the increased livetime between O2 and O3. For comparison, estimated merger rates from the second LIGO-Virgo GW transient catalogue [52] are $23.9^{+14.3}_{-8.6} \text{ Gpc}^{-3} \text{yr}^{-1}$ and $340^{+490}_{-240} \text{ Gpc}^{-3} \text{yr}^{-1}$ for binary black holes and binary neutron stars respectively. With eccentric systems expected to be only a fraction of the total binary systems, the upper limits derived are compatible with an absence of detection in this search.

It is expected that continued improvements both to the gravitational-wave detectors and to the search algorithms, e.g. [48, 53, 54], will lead to either detections or improved limits on this portion of parameter space. Going forward, increasing the parameter space searched, such as for longer signals, is a high priority; these signals may include long-lived remnants of binary neutron star mergers, whose detection in gravitational waves may constrain the nature of the remnant [12, 25]. In addition, integration of Advanced Virgo into the analyses will be important, especially in case of a genuine signal for characterization. With range improvements of $\sim 50\%$ expected for the fourth observing run and more than a factor of 2 expected by the fifth observing run [26], significant gains

in detection possibilities can be expected.

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R. Abbott,¹ T. D. Abbott,² F. Acernese,^{3,4} K. Ackley,⁵ C. Adams,⁶ N. Adhikari,⁷ R. X. Adhikari,¹ V. B. Adya,⁸ C. Affeldt,^{9,10} D. Agarwal,¹¹ M. Agathos,^{12,13} K. Agatsuma,¹⁴ N. Aggarwal,¹⁵ O. D. Aguiar,¹⁶ L. Aiello,¹⁷ A. Ain,¹⁸ P. Ajith,¹⁹ T. Akutsu,^{20,21} S. Albanesi,²² A. Allocca,^{23,4} P. A. Altin,⁸ A. Amato,²⁴ C. Anand,⁵ S. Anand,¹ A. Ananyeva,¹ S. B. Anderson,¹ W. G. Anderson,⁷ M. Ando,^{25,26} T. Andrade,²⁷ N. Andres,²⁸ T. Andrić,²⁹ S. V. Angelova,³⁰ S. Ansoldi,^{31,32} J. M. Antelis,³³ S. Antier,³⁴ S. Appert,¹ Koji Arai,¹ Koya Arai,³⁵ Y. Arai,³⁵ S. Araki,³⁶ A. Araya,³⁷ M. C. Araya,¹ J. S. Areeda,³⁸ M. Arène,³⁴ N. Aritomi,²⁵ N. Arnaud,^{39,40} S. M. Aronson,² K. G. Arun,⁴¹ H. Asada,⁴² Y. Asali,⁴³ G. Ashton,⁵ Y. Aso,^{44,45} M. Assiduo,^{46,47} S. M. Aston,⁶ P. Astone,⁴⁸ F. Aubin,²⁸ C. Austin,² S. Babak,³⁴ F. Badaracco,⁴⁹ M. K. M. Bader,⁵⁰ C. Badger,⁵¹ S. Bae,⁵² Y. Bae,⁵³ A. M. Baer,⁵⁴ S. Bagnasco,²² Y. Bai,¹ L. Baiotti,⁵⁵ J. Baird,³⁴ R. Bajpai,⁵⁶ M. Ball,⁵⁷ G. Ballardín,⁴⁰ S. W. Ballmer,⁵⁸ A. Balsamo,⁵⁴ G. Baltus,⁵⁹ S. Banagiri,⁶⁰ D. Bankar,¹¹ J. C. Barayoga,¹ C. Barbieri,^{61,62,63} B. C. Barish,¹ D. Barker,⁶⁴ P. Barneo,²⁷ F. Barone,^{65,4} B. Barr,⁶⁶ L. Barsotti,⁶⁷ M. Barsuglia,³⁴ D. Barta,⁶⁸ J. Bartlett,⁶⁴ M. A. Barton,^{66,20} I. Bartos,⁶⁹ R. Bassiri,⁷⁰ A. Basti,^{71,18} M. Bawaj,^{72,73} J. C. Bayley,⁶⁶ A. C. Baylor,⁷ M. Bazzan,^{74,75} B. Bécsy,⁷⁶ V. M. Bedakihale,⁷⁷ M. Bejger,⁷⁸ I. Belahcene,³⁹ V. Benedetto,⁷⁹ D. Beniwal,⁸⁰ T. F. Bennett,⁸¹ J. D. Bentley,¹⁴ M. BenYaala,³⁰ F. Bergamin,^{9,10} B. K. Berger,⁷⁰ S. Bernuzzi,¹³ D. Bersanetti,⁸² A. Bertolini,⁵⁰ J. Betzwieser,⁶ D. Beveridge,⁸³ R. Bhandare,⁸⁴ U. Bhardwaj,^{85,50} D. Bhattacharjee,⁸⁶ S. Bhaumik,⁶⁹ I. A. Bilenko,⁸⁷ G. Billingsley,¹ S. Bini,^{88,89} R. Birney,⁹⁰ O. Birnholtz,⁹¹ S. Biscans,^{1,67} M. Bischì,^{46,47} S. Biscoveanu,⁶⁷ A. Bisht,^{9,10} B. Biswas,¹¹ M. Bitossi,^{40,18} M.-A. Bizouard,⁹² J. K. Blackburn,¹ C. D. Blair,^{83,6} D. G. Blair,⁸³ R. M. Blair,⁶⁴ F. Bobba,^{93,94} N. Bode,^{9,10} M. Boer,⁹² G. Bogaert,⁹² M. Boldrini,^{95,48} L. D. Bonavena,⁷⁴ F. Bondu,⁹⁶ E. Bonilla,⁷⁰ R. Bonnand,²⁸ P. Booker,^{9,10} B. A. Boom,⁵⁰ R. Bork,¹ V. Boschi,¹⁸ N. Bose,⁹⁷ S. Bose,¹¹ V. Bossilkov,⁸³ V. Boudart,⁵⁹ Y. Bouffanaïs,^{74,75} A. Bozzi,⁴⁰ C. Bradaschia,¹⁸ P. R. Brady,⁷ A. Bramley,⁶ A. Branch,⁶ M. Branchesi,^{29,98} J. E. Brau,⁵⁷ M. Breschi,¹³ T. Briant,⁹⁹ J. H. Briggs,⁶⁶ A. Brillet,⁹² M. Brinkmann,^{9,10} P. Brockill,⁷ A. F. Brooks,¹ J. Brooks,⁴⁰ D. D. Brown,⁸⁰ S. Brunett,¹ G. Bruno,⁴⁹ R. Bruntz,⁵⁴ J. Bryant,¹⁴ T. Bulik,¹⁰⁰ H. J. Bulten,⁵⁰ A. Buonanno,^{101,102} R. Buscicchio,¹⁴ D. Buskulic,²⁸ C. Buy,¹⁰³ R. L. Byer,⁷⁰ L. Cadonati,¹⁰⁴ G. Cagnoli,²⁴ C. Cahillane,⁶⁴ J. Calderón Bustillo,^{105,106} J. D. Callaghan,⁶⁶ T. A. Callister,^{107,108} E. Calloni,^{23,4} J. Cameron,⁸³ J. B. Camp,¹⁰⁹ M. Canepa,^{110,82} S. Canevarolo,¹¹¹ M. Cannavacciuolo,⁹³ K. C. Cannon,¹¹² H. Cao,⁸⁰ Z. Cao,¹¹³ E. Capocasa,²⁰ E. Capote,⁵⁸ G. Carapella,^{93,94} F. Carbognani,⁴⁰ J. B. Carlin,¹¹⁴ M. F. Carney,¹⁵ M. Carpinelli,^{115,116,40} G. Carrillo,⁵⁷ G. Carullo,^{71,18} T. L. Carver,¹⁷ J. Casanueva Diaz,⁴⁰ C. Casentini,^{117,118} G. Castaldi,¹¹⁹ S. Caudill,^{50,111} M. Cavaglià,⁸⁶ F. Cavalier,³⁹ R. Cavalieri,⁴⁰ M. Ceasar,¹²⁰ G. Cella,¹⁸ P. Cerdá-Durán,¹²¹ E. Cesarini,¹¹⁸ W. Chaibi,⁹² K. Chakravarti,¹¹ S. Chalathadka Subrahmanya,¹²² E. Champion,¹²³ C.-H. Chan,¹²⁴ C. Chan,¹¹² C. L. Chan,¹⁰⁶ K. Chan,¹⁰⁶ M. Chan,¹²⁵ K. Chandra,⁹⁷ P. Chanial,⁴⁰ S. Chao,¹²⁴ P. Charlton,¹²⁶ E. A. Chase,¹⁵ E. Chassande-Mottin,³⁴ C. Chatterjee,⁸³ Debarati Chatterjee,¹¹ Deep Chatterjee,⁷ M. Chaturvedi,⁸⁴ S. Chaty,³⁴ C. Chen,^{127,128} H. Y. Chen,⁶⁷ J. Chen,¹²⁴ K. Chen,¹²⁹ X. Chen,⁸³ Y.-B. Chen,¹³⁰ Y.-R. Chen,¹³¹ Z. Chen,¹⁷ H. Cheng,⁶⁹ C. K. Cheong,¹⁰⁶ H. Y. Cheung,¹⁰⁶ H. Y. Chia,⁶⁹ F. Chiadini,^{132,94} C.-Y. Chiang,¹³³ G. Chiarini,⁷⁵ R. Chierici,¹³⁴ A. Chincarini,⁸² M. L. Chiofalo,^{71,18} A. Chiummo,⁴⁰ G. Cho,¹³⁵ H. S. Cho,¹³⁶ R. K. Choudhary,⁸³ S. Choudhary,¹¹ N. Christensen,⁹² H. Chu,¹²⁹ Q. Chu,⁸³ Y.-K. Chu,¹³³ S. Chua,⁸ K. W. Chung,⁵¹ G. Ciani,^{74,75} P. Cieciela,⁷⁸ M. Cieřlar,⁷⁸ M. Cifaldi,^{117,118} A. A. Ciobanu,⁸⁰ R. Ciolfi,^{137,75} F. Cipriano,⁹² A. Cirone,^{110,82} F. Clara,⁶⁴ E. N. Clark,¹³⁸ J. A. Clark,^{1,104} L. Clarke,¹³⁹ P. Clearwater,¹⁴⁰ S. Clesse,¹⁴¹ F. Cleva,⁹² E. Coccia,^{29,98} E. Codazzo,²⁹ P.-F. Cohadon,⁹⁹ D. E. Cohen,³⁹ L. Cohen,² M. Colleoni,¹⁴² C. G. Collette,¹⁴³ A. Colombo,⁶¹ M. Colpi,^{61,62} C. M. Compton,⁶⁴ M. Constancio Jr.,¹⁶ L. Conti,⁷⁵ S. J. Cooper,¹⁴ P. Corban,⁶ T. R. Corbitt,² I. Cordero-Carrión,¹⁴⁴ S. Corezzi,^{73,72} K. R. Corley,⁴³ N. Cornish,⁷⁶ D. Corre,³⁹ A. Corsi,¹⁴⁵ S. Cortese,⁴⁰ C. A. Costa,¹⁶ R. Cotesta,¹⁰² M. W. Coughlin,⁶⁰ J.-P. Coulon,⁹² S. T. Countryman,⁴³ B. Cousins,¹⁴⁶ P. Couvares,¹ D. M. Coward,⁸³ M. J. Cowart,⁶ D. C. Coyne,¹ R. Coyne,¹⁴⁷ J. D. E. Creighton,⁷ T. D. Creighton,¹⁴⁸ A. W. Criswell,⁶⁰ M. Croquette,⁹⁹ S. G. Crowder,¹⁴⁹ J. R. Cudell,⁵⁹ T. J. Cullen,² A. Cumming,⁶⁶ R. Cummings,⁶⁶ L. Cunningham,⁶⁶ E. Cuoco,^{40,150,18} M. Curylo,¹⁰⁰ P. Dabadie,²⁴ T. Dal Canton,³⁹ S. Dall'Osso,²⁹ G. Dálya,¹⁵¹ A. Dana,⁷⁰ L. M. DaneshgaranBajastani,⁸¹ B. D'Angelo,^{110,82} S. Danilishin,^{152,50} S. D'Antonio,¹¹⁸ K. Danzmann,^{9,10} C. Darsow-Fromm,¹²² A. Dasgupta,⁷⁷ L. E. H. Datrier,⁶⁶ S. Datta,¹¹ V. Dattilo,⁴⁰ I. Dave,⁸⁴ M. Davier,³⁹ G. S. Davies,¹⁵³ D. Davis,¹ M. C. Davis,¹²⁰ E. J. Daw,¹⁵⁴ R. Dean,¹²⁰ D. DeBra,⁷⁰ M. Deenadayalan,¹¹ J. Degallaix,¹⁵⁵ M. De Laurentis,^{23,4} S. Deléglise,⁹⁹ V. Del Favero,¹²³ F. De Lillo,⁴⁹ N. De Lillo,⁶⁶ W. Del Pozzo,^{71,18} L. M. DeMarchi,¹⁵ F. De Matteis,^{117,118} V. D'Emilio,¹⁷ N. Demos,⁶⁷ T. Dent,¹⁰⁵ A. Depasse,⁴⁹ R. De Pietri,^{156,157} R. De Rosa,^{23,4} C. De Rossi,⁴⁰ R. DeSalvo,¹¹⁹ R. De Simone,¹³² S. Dhurandhar,¹¹ M. C. Díaz,¹⁴⁸ M. Diaz-Ortiz Jr.,⁶⁹ N. A. Didio,⁵⁸ T. Dietrich,^{102,50} L. Di Fiore,⁴ C. Di

- Fronzo,¹⁴ C. Di Giorgio,^{93,94} F. Di Giovanni,¹²¹ M. Di Giovanni,²⁹ T. Di Girolamo,^{23,4} A. Di Lieto,^{71,18} B. Ding,¹⁴³ S. Di Pace,^{95,48} I. Di Palma,^{95,48} F. Di Renzo,^{71,18} A. K. Divakarla,⁶⁹ A. Dmitriev,¹⁴ Z. Doctor,⁵⁷ L. D'Onofrio,^{23,4} F. Donovan,⁶⁷ K. L. Dooley,¹⁷ S. Doravari,¹¹ I. Dorrington,¹⁷ M. Drago,^{95,48} J. C. Driggers,⁶⁴ Y. Drori,¹ J.-G. Ducoin,³⁹ P. Dupej,⁶⁶ O. Durante,^{93,94} D. D'Urso,^{115,116} P.-A. Duverne,³⁹ S. E. Dwyer,⁶⁴ C. Eassa,⁶⁴ P. J. Easter,⁵ M. Ebersold,¹⁵⁸ T. Eckhardt,¹²² G. Eddolls,⁶⁶ B. Edelman,⁵⁷ T. B. Edo,¹ O. Edy,¹⁵³ A. Effler,⁶ S. Eguchi,¹²⁵ J. Eichholz,⁸ S. S. Eikenberry,⁶⁹ M. Eisenmann,²⁸ R. A. Eisenstein,⁶⁷ A. Ejlli,¹⁷ E. Engelby,³⁸ Y. Enomoto,²⁵ L. Errico,^{23,4} R. C. Essick,¹⁵⁹ H. Estellés,¹⁴² D. Estevez,¹⁶⁰ Z. Etienne,¹⁶¹ T. Etzel,¹ M. Evans,⁶⁷ T. M. Evans,⁶ B. E. Ewing,¹⁴⁶ V. Fafone,^{117,118,29} H. Fair,⁵⁸ S. Fairhurst,¹⁷ A. M. Farah,¹⁵⁹ S. Farinon,⁸² B. Farr,⁵⁷ W. M. Farr,^{107,108} N. W. Farrow,⁵ E. J. Fauchon-Jones,¹⁷ G. Favaro,⁷⁴ M. Favata,¹⁶² M. Fays,⁵⁹ M. Fazio,¹⁶³ J. Feicht,¹ M. M. Fejer,⁷⁰ E. Fenyvesi,^{68,164} D. L. Ferguson,¹⁶⁵ A. Fernandez-Galiana,⁶⁷ I. Ferrante,^{71,18} T. A. Ferreira,¹⁶ F. Fidecaro,^{71,18} P. Figura,¹⁰⁰ I. Fiori,⁴⁰ M. Fishbach,¹⁵ R. P. Fisher,⁵⁴ R. Fittipaldi,^{166,94} V. Fiumara,^{167,94} R. Flamini,^{28,20} E. Floden,⁶⁰ H. Fong,¹¹² J. A. Font,^{121,168} B. Fornal,¹⁶⁹ P. W. F. Forsyth,⁸ A. Franke,¹²² S. Frasca,^{95,48} F. Frasconi,¹⁸ C. Frederick,¹⁷⁰ J. P. Freed,³³ Z. Frei,¹⁵¹ A. Freise,¹⁷¹ R. Frey,⁵⁷ P. Fritschel,⁶⁷ V. V. Frolov,⁶ G. G. Fronzé,²² Y. Fujii,¹⁷² Y. Fujikawa,¹⁷³ M. Fukunaga,³⁵ M. Fukushima,²¹ P. Fulda,⁶⁹ M. Fyffe,⁶ H. A. Gabbard,⁶⁶ B. U. Gadre,¹⁰² J. R. Gair,¹⁰² J. Gais,¹⁰⁶ S. Galaudage,⁵ R. Gamba,¹³ D. Ganapathy,⁶⁷ A. Ganguly,¹⁹ D. Gao,¹⁷⁴ S. G. Gaonkar,¹¹ B. Garaventa,^{82,110} C. García-Núñez,⁹⁰ C. García-Quirós,¹⁴² F. Garufi,^{23,4} B. Gateley,⁶⁴ S. Gaudio,³³ V. Gayathri,⁶⁹ G.-G. Ge,¹⁷⁴ G. Gemme,⁸² A. Gennai,¹⁸ J. George,⁸⁴ O. Gerberding,¹²² L. Gergely,¹⁷⁵ P. Gewecke,¹²² S. Ghonge,¹⁰⁴ Abhirup Ghosh,¹⁰² Archisman Ghosh,¹⁷⁶ Shaon Ghosh,^{7,162} Shrobona Ghosh,¹⁷ B. Giacomazzo,^{61,62,63} L. Giaccoppo,^{95,48} J. A. Giaime,^{2,6} K. D. Giardina,⁶ D. R. Gibson,⁹⁰ C. Gier,³⁰ M. Giesler,¹⁷⁷ P. Giri,^{18,71} F. Gissi,⁷⁹ J. Glanzer,² A. E. Gleckl,³⁸ P. Godwin,¹⁴⁶ E. Goetz,¹⁷⁸ R. Goetz,⁶⁹ N. Gohlke,^{9,10} B. Goncharov,^{5,29} G. González,² A. Gopakumar,¹⁷⁹ M. Gosselin,⁴⁰ R. Gouaty,²⁸ D. W. Gould,⁸ B. Grace,⁸ A. Grado,^{180,4} M. Granata,¹⁵⁵ V. Granata,⁹³ A. Grant,⁶⁶ S. Gras,⁶⁷ P. Grassia,¹ C. Gray,⁶⁴ R. Gray,⁶⁶ G. Greco,⁷² A. C. Green,⁶⁹ R. Green,¹⁷ A. M. Gretarsson,³³ E. M. Gretarsson,³³ D. Griffith,¹ W. Griffiths,¹⁷ H. L. Griggs,¹⁰⁴ G. Grignani,^{73,72} A. Grimaldi,^{88,89} S. J. Grimm,^{29,98} H. Grote,¹⁷ S. Grunewald,¹⁰² P. Gruning,³⁹ D. Guerra,¹²¹ G. M. Guidi,^{46,47} A. R. Guimaraes,² G. Guixé,²⁷ H. K. Gulati,⁷⁷ H.-K. Guo,¹⁶⁹ Y. Guo,⁵⁰ Anchal Gupta,¹ Anuradha Gupta,¹⁸¹ P. Gupta,^{50,111} E. K. Gustafson,¹ R. Gustafson,¹⁸² F. Guzman,¹⁸³ S. Ha,¹⁸⁴ L. Haegel,³⁴ A. Hagiwara,^{35,185} S. Haino,¹³³ O. Halim,^{32,186} E. D. Hall,⁶⁷ E. Z. Hamilton,¹⁵⁸ G. Hammond,⁶⁶ W.-B. Han,¹⁸⁷ M. Haney,¹⁵⁸ J. Hanks,⁶⁴ C. Hanna,¹⁴⁶ M. D. Hannam,¹⁷ O. Hannuksela,^{111,50} H. Hansen,⁶⁴ T. J. Hansen,³³ J. Hanson,⁶ T. Harder,⁹² T. Hardwick,² K. Haris,^{50,111} J. Harms,^{29,98} G. M. Harry,¹⁸⁸ I. W. Harry,¹⁵³ D. Hartwig,¹²² K. Hasegawa,³⁵ B. Haskell,⁷⁸ R. K. Hasskew,⁶ C.-J. Haster,⁶⁷ K. Hattori,¹⁸⁹ K. Haughian,⁶⁶ H. Hayakawa,¹⁹⁰ K. Hayama,¹²⁵ F. J. Hayes,⁶⁶ J. Healy,¹²³ A. Heidmann,⁹⁹ A. Heidt,^{9,10} M. C. Heintze,⁶ J. Heinze,^{9,10} J. Heinzl,¹⁹¹ H. Heitmann,⁹² F. Hellman,¹⁹² P. Hello,³⁹ A. F. Helmling-Cornell,⁵⁷ G. Hemming,⁴⁰ M. Hendry,⁶⁶ I. S. Heng,⁶⁶ E. Hennes,⁵⁰ J. Hennig,¹⁹³ M. H. Hennig,¹⁹³ A. G. Hernandez,⁸¹ F. Hernandez Vivanco,⁵ M. Heurs,^{9,10} S. Hild,^{152,50} P. Hill,³⁰ Y. Himemoto,¹⁹⁴ A. S. Hines,¹⁸³ Y. Hiranuma,¹⁹⁵ N. Hirata,²⁰ E. Hirose,³⁵ S. Hochheim,^{9,10} D. Hofman,¹⁵⁵ J. N. Hohmann,¹²² D. G. Holcomb,¹²⁰ N. A. Holland,⁸ I. J. Hollows,¹⁵⁴ Z. J. Holmes,⁸⁰ K. Holt,⁶ D. E. Holz,¹⁵⁹ Z. Hong,¹⁹⁶ P. Hopkins,¹⁷ J. Hough,⁶⁶ S. Hourihane,¹³⁰ E. J. Howell,⁸³ C. G. Hoy,¹⁷ D. Hoyland,¹⁴ A. Hreibi,^{9,10} B.-H. Hsieh,³⁵ Y. Hsu,¹²⁴ G.-Z. Huang,¹⁹⁶ H.-Y. Huang,¹³³ P. Huang,¹⁷⁴ Y.-C. Huang,¹³¹ Y.-J. Huang,¹³³ Y. Huang,⁶⁷ M. T. Hübner,⁵ A. D. Huddart,¹³⁹ B. Hughey,³³ D. C. Y. Hui,¹⁹⁷ V. Hui,²⁸ S. Husa,¹⁴² S. H. Huttner,⁶⁶ R. Huxford,¹⁴⁶ T. Huynh-Dinh,⁶ S. Ide,¹⁹⁸ B. Idzkowski,¹⁰⁰ A. Iess,^{117,118} B. Ikenoue,²¹ S. Imam,¹⁹⁶ K. Inayoshi,¹⁹⁹ C. Ingram,⁸⁰ Y. Inoue,¹²⁹ K. Ioka,²⁰⁰ M. Isi,⁶⁷ K. Isleif,¹²² K. Ito,²⁰¹ Y. Itoh,^{202,203} B. R. Iyer,¹⁹ K. Izumi,²⁰⁴ V. JaberianHamedan,⁸³ T. Jacqmin,⁹⁹ S. J. Jadhav,²⁰⁵ S. P. Jadhav,¹¹ A. L. James,¹⁷ A. Z. Jan,¹²³ K. Jani,²⁰⁶ J. Janquart,^{111,50} K. Janssens,^{207,92} N. N. Janthalur,²⁰⁵ P. Jaranowski,²⁰⁸ D. Jariwala,⁶⁹ R. Jaume,¹⁴² A. C. Jenkins,⁵¹ K. Jenner,⁸⁰ C. Jeon,²⁰⁹ M. Jeunon,⁶⁰ W. Jia,⁶⁷ H.-B. Jin,^{210,211} G. R. Johns,⁵⁴ A. W. Jones,⁸³ D. I. Jones,²¹² J. D. Jones,⁶⁴ P. Jones,¹⁴ R. Jones,⁶⁶ R. J. G. Jonker,⁵⁰ L. Ju,⁸³ P. Jung,⁵³ k. Jung,¹⁸⁴ J. Junker,^{9,10} V. Juste,¹⁶⁰ K. Kaihotsu,²⁰¹ T. Kajita,²¹³ M. Kakizaki,¹⁸⁹ C. V. Kalaghatgi,^{17,111} V. Kalogera,¹⁵ B. Kamai,¹ M. Kamiizumi,¹⁹⁰ N. Kanda,^{202,203} S. Kandhasamy,¹¹ G. Kang,²¹⁴ J. B. Kanner,¹ Y. Kao,¹²⁴ S. J. Kapadia,¹⁹ D. P. Kapasi,⁸ S. Karat,¹ C. Karathanasis,²¹⁵ S. Karki,⁸⁶ R. Kashyap,¹⁴⁶ M. Kasprzak,¹ W. Kastaun,^{9,10} S. Katsanevas,⁴⁰ E. Katsavounidis,⁶⁷ W. Katzman,⁶ T. Kaur,⁸³ K. Kawabe,⁶⁴ K. Kawaguchi,³⁵ N. Kawai,²¹⁶ T. Kawasaki,²⁵ F. Kéfélian,⁹² D. Keitel,¹⁴² J. S. Key,²¹⁷ S. Khadka,⁷⁰ F. Y. Khalili,⁸⁷ S. Khan,¹⁷ E. A. Khazanov,²¹⁸ N. Khetan,^{29,98} M. Khursheed,⁸⁴ N. Kijbunchoo,⁸ C. Kim,²¹⁹ J. C. Kim,²²⁰ J. Kim,²²¹ K. Kim,²²² W. S. Kim,²²³ Y.-M. Kim,²²⁴ C. Kimball,¹⁵ N. Kimura,¹⁸⁵ M. Kinley-Hanlon,⁶⁶ R. Kirchhoff,^{9,10} J. S. Kissel,⁶⁴ N. Kita,²⁵ H. Kitazawa,²⁰¹ L. Kleybolte,¹²² S. Klimenko,⁶⁹ A. M. Knee,¹⁷⁸

- T. D. Knowles,¹⁶¹ E. Knyazev,⁶⁷ P. Koch,^{9, 10} G. Koekoek,^{50, 152} Y. Kojima,²²⁵ K. Kokeyama,²²⁶ S. Koley,²⁹ P. Kolitsidou,¹⁷ M. Kolstein,²¹⁵ K. Komori,^{67, 25} V. Kondrashov,¹ A. K. H. Kong,²²⁷ A. Kontos,²²⁸ N. Koper,^{9, 10} M. Korobko,¹²² K. Kotake,¹²⁵ M. Kovalam,⁸³ D. B. Kozak,¹ C. Kozakai,⁴⁴ R. Kozu,¹⁹⁰ V. Kringel,^{9, 10} N. V. Krishnendu,^{9, 10} A. Królak,^{229, 230} G. Kuehn,^{9, 10} F. Kuei,¹²⁴ P. Kuijer,⁵⁰ A. Kumar,²⁰⁵ P. Kumar,¹⁷⁷ Rahul Kumar,⁶⁴ Rakesh Kumar,⁷⁷ J. Kume,²⁶ K. Kuns,⁶⁷ C. Kuo,¹²⁹ H-S. Kuo,¹⁹⁶ Y. Kuromiya,²⁰¹ S. Kuroyanagi,^{231, 232} K. Kusayanagi,²¹⁶ S. Kuwahara,¹¹² K. Kwak,¹⁸⁴ P. Lagabbe,²⁸ D. Laghi,^{71, 18} E. Lalande,²³³ T. L. Lam,¹⁰⁶ A. Lamberts,^{92, 234} M. Landry,⁶⁴ B. B. Lane,⁶⁷ R. N. Lang,⁶⁷ J. Lange,¹⁶⁵ B. Lantz,⁷⁰ I. La Rosa,²⁸ A. Lartaux-Vollard,³⁹ P. D. Lasky,⁵ M. Laxen,⁶ A. Lazzarini,¹ C. Lazzaro,^{74, 75} P. Leaci,^{95, 48} S. Leavey,^{9, 10} Y. K. Lecoeuche,¹⁷⁸ H. K. Lee,²³⁵ H. M. Lee,¹³⁵ H. W. Lee,²²⁰ J. Lee,¹³⁵ K. Lee,²³⁶ R. Lee,¹³¹ J. Lehmann,^{9, 10} A. Lemaître,²³⁷ M. Leonardi,²⁰ N. Leroy,³⁹ N. Letendre,²⁸ C. Levesque,²³³ Y. Levin,⁵ J. N. Leviton,¹⁸² K. Leyde,³⁴ A. K. Y. Li,¹ B. Li,¹²⁴ J. Li,¹⁵ K. L. Li,²³⁸ T. G. F. Li,¹⁰⁶ X. Li,¹³⁰ C-Y. Lin,²³⁹ F-K. Lin,¹³³ F-L. Lin,¹⁹⁶ H. L. Lin,¹²⁹ L. C.-C. Lin,¹⁸⁴ F. Linde,^{240, 50} S. D. Linker,⁸¹ J. N. Linley,⁶⁶ T. B. Littenberg,²⁴¹ G. C. Liu,¹²⁷ J. Liu,^{9, 10} K. Liu,¹²⁴ X. Liu,⁷ F. Llamas,¹⁴⁸ M. Llorens-Monteagudo,¹²¹ R. K. L. Lo,¹ A. Lockwood,²⁴² L. T. London,⁶⁷ A. Longo,^{243, 244} D. Lopez,¹⁵⁸ M. Lopez Portilla,¹¹¹ M. Lorenzini,^{117, 118} V. Lorette,²⁴⁵ M. Lormand,⁶ G. Losurdo,¹⁸ T. P. Lott,¹⁰⁴ J. D. Lough,^{9, 10} C. O. Lousto,¹²³ G. Lovelace,³⁸ J. F. Lucaccioni,¹⁷⁰ H. Lück,^{9, 10} D. Lumaca,^{117, 118} A. P. Lundgren,¹⁵³ L.-W. Luo,¹³³ J. E. Lynam,⁵⁴ R. Macas,¹⁵³ M. MacInnis,⁶⁷ D. M. Macleod,¹⁷ I. A. O. MacMillan,¹ A. Macquet,⁹² I. Magaña Hernandez,⁷ C. Magazzù,¹⁸ R. M. Magee,¹ R. Maggiore,¹⁴ M. Magnozzi,^{82, 110} S. Mahesh,¹⁶¹ E. Majorana,^{95, 48} C. Makarem,¹ I. Maksimovic,²⁴⁵ S. Maliakal,¹ A. Malik,⁸⁴ N. Man,⁹² V. Mandic,⁶⁰ V. Mangano,^{95, 48} J. L. Mango,²⁴⁶ G. L. Mansell,^{64, 67} M. Manske,⁷ M. Mantovani,⁴⁰ M. Mapelli,^{74, 75} F. Marchesoni,^{247, 72, 248} M. Marchio,²⁰ F. Marion,²⁸ Z. Mark,¹³⁰ S. Márka,⁴³ Z. Márka,⁴³ C. Markakis,¹² A. S. Markosyan,⁷⁰ A. Markowitz,¹ E. Maros,¹ A. Marquina,¹⁴⁴ S. Marsat,³⁴ F. Martelli,^{46, 47} I. W. Martin,⁶⁶ R. M. Martin,¹⁶² M. Martinez,²¹⁵ V. A. Martinez,⁶⁹ V. Martinez,²⁴ K. Martinovic,⁵¹ D. V. Martynov,¹⁴ E. J. Marx,⁶⁷ H. Masalehdan,¹²² K. Mason,⁶⁷ E. Massera,¹⁵⁴ A. Masserot,²⁸ T. J. Massinger,⁶⁷ M. Masso-Reid,⁶⁶ S. Mastrogiovanni,³⁴ A. Matas,¹⁰² M. Mateu-Lucena,¹⁴² F. Matichard,^{1, 67} M. Matushechkina,^{9, 10} N. Mavalvala,⁶⁷ J. J. McCann,⁸³ R. McCarthy,⁶⁴ D. E. McClelland,⁸ P. K. McClincy,¹⁴⁶ S. McCormick,⁶ L. McCuller,⁶⁷ G. I. McGhee,⁶⁶ S. C. McGuire,²⁴⁹ C. McIsaac,¹⁵³ J. McIver,¹⁷⁸ T. McRae,⁸ S. T. McWilliams,¹⁶¹ D. Meacher,⁷ M. Mehmet,^{9, 10} A. K. Mehta,¹⁰² Q. Meijer,¹¹¹ A. Melatos,¹¹⁴ D. A. Melchor,³⁸ G. Mendell,⁶⁴ A. Menendez-Vazquez,²¹⁵ C. S. Menoni,¹⁶³ R. A. Mercer,⁷ L. Mereni,¹⁵⁵ K. Merfeld,⁵⁷ E. L. Merilh,⁶ J. D. Merritt,⁵⁷ M. Merzougui,⁹² S. Meshkov,^{1, a} C. Messenger,⁶⁶ C. Messick,¹⁶⁵ P. M. Meyers,¹¹⁴ F. Meylahn,^{9, 10} A. Mhaske,¹¹ A. Miani,^{88, 89} H. Miao,¹⁴ I. Michaloliakos,⁶⁹ C. Michel,¹⁵⁵ Y. Michimura,²⁵ H. Middleton,¹¹⁴ L. Milano,²³ A. L. Miller,⁴⁹ A. Miller,⁸¹ B. Miller,^{85, 50} M. Millhouse,¹¹⁴ J. C. Mills,¹⁷ E. Milotti,^{186, 32} O. Minazzoli,^{92, 250} Y. Minenkov,¹¹⁸ N. Mio,²⁵¹ Ll. M. Mir,²¹⁵ M. Miravet-Tenés,¹²¹ C. Mishra,²⁵² T. Mishra,⁶⁹ T. Mistry,¹⁵⁴ S. Mitra,¹¹ V. P. Mitrofanov,⁸⁷ G. Mitselmakher,⁶⁹ R. Mittleman,⁶⁷ O. Miyakawa,¹⁹⁰ A. Miyamoto,²⁰² Y. Miyazaki,²⁵ K. Miyo,¹⁹⁰ S. Miyoki,¹⁹⁰ Geoffrey Mo,⁶⁷ E. Moguel,¹⁷⁰ K. Mogushi,⁸⁶ S. R. P. Mohapatra,⁶⁷ S. R. Mohite,⁷ I. Molina,³⁸ M. Molina-Ruiz,¹⁹² M. Mondin,⁸¹ M. Montani,^{46, 47} C. J. Moore,¹⁴ D. Moraru,⁶⁴ F. Morawski,⁷⁸ A. More,¹¹ C. Moreno,³³ G. Moreno,⁶⁴ Y. Mori,²⁰¹ S. Morisaki,⁷ Y. Moriwaki,¹⁸⁹ B. Mours,¹⁶⁰ C. M. Mow-Lowry,^{14, 171} S. Mozzon,¹⁵³ F. Muciaccia,^{95, 48} Arunava Mukherjee,²⁵³ D. Mukherjee,¹⁴⁶ Soma Mukherjee,¹⁴⁸ Subroto Mukherjee,⁷⁷ Suvodip Mukherjee,⁸⁵ N. Mukund,^{9, 10} A. Mullavey,⁶ J. Munch,⁸⁰ E. A. Muñoz,⁵⁸ P. G. Murray,⁶⁶ R. Musenich,^{82, 110} S. Muusse,⁸⁰ S. L. Nadjji,^{9, 10} K. Nagano,²⁰⁴ S. Nagano,²⁵⁴ A. Nagar,^{22, 255} K. Nakamura,²⁰ H. Nakano,²⁵⁶ M. Nakano,³⁵ R. Nakashima,²¹⁶ Y. Nakayama,²⁰¹ V. Napolano,⁴⁰ I. Nardecchia,^{117, 118} T. Narikawa,³⁵ L. Naticchioni,⁴⁸ B. Nayak,⁸¹ R. K. Nayak,²⁵⁷ R. Negishi,¹⁹⁵ B. F. Neil,⁸³ J. Neilson,^{79, 94} G. Nelemans,²⁵⁸ T. J. N. Nelson,⁶ M. Nery,^{9, 10} P. Neubauer,¹⁷⁰ A. Neunzert,²¹⁷ K. Y. Ng,⁶⁷ S. W. S. Ng,⁸⁰ C. Nguyen,³⁴ P. Nguyen,⁵⁷ T. Nguyen,⁶⁷ L. Nguyen Quynh,²⁵⁹ W.-T. Ni,^{210, 174, 131} S. A. Nichols,² A. Nishizawa,²⁶ S. Nissanke,^{85, 50} E. Nitoglia,¹³⁴ F. Nocera,⁴⁰ M. Norman,¹⁷ C. North,¹⁷ S. Nozaki,¹⁸⁹ L. K. Nuttall,¹⁵³ J. Oberling,⁶⁴ B. D. O'Brien,⁶⁹ Y. Obuchi,²¹ J. O'Dell,¹³⁹ E. Oelker,⁶⁶ W. Ogaki,³⁵ G. Oganessian,^{29, 98} J. J. Oh,²²³ K. Oh,¹⁹⁷ S. H. Oh,²²³ M. Ohashi,¹⁹⁰ N. Ohishi,⁴⁴ M. Ohkawa,¹⁷³ F. Ohme,^{9, 10} H. Ohta,¹¹² M. A. Okada,¹⁶ Y. Okutani,¹⁹⁸ K. Okutomi,¹⁹⁰ C. Olivetto,⁴⁰ K. Oohara,¹⁹⁵ C. Ooi,²⁵ R. Oram,⁶ B. O'Reilly,⁶ R. G. Ormiston,⁶⁰ N. D. Ormsby,⁵⁴ L. F. Ortega,⁶⁹ R. O'Shaughnessy,¹²³ E. O'Shea,¹⁷⁷ S. Oshino,¹⁹⁰ S. Ossokine,¹⁰² C. Osthelder,¹ S. Otabe,²¹⁶ D. J. Ottaway,⁸⁰ H. Overmier,⁶ A. E. Pace,¹⁴⁶ G. Pagano,^{71, 18} M. A. Page,⁸³ G. Pagliaroli,^{29, 98} A. Pai,⁹⁷ S. A. Pai,⁸⁴ J. R. Palamos,⁵⁷ O. Palashov,²¹⁸ C. Palomba,⁴⁸ H. Pan,¹²⁴ K. Pan,^{131, 227} P. K. Panda,²⁰⁵ H. Pang,¹²⁹ P. T. H. Pang,^{50, 111} C. Pankow,¹⁵ F. Pannarale,^{95, 48} B. C. Pant,⁸⁴ F. H. Panther,⁸³ F. Paoletti,¹⁸ A. Paoli,⁴⁰ A. Paolone,^{48, 260} A. Parisi,¹²⁷ H. Park,⁷ J. Park,²⁶¹ W. Parker,^{6, 249} D. Pascucci,⁵⁰ A. Pasqualetti,⁴⁰ R. Passaquietti,^{71, 18} D. Passuello,¹⁸ M. Patel,⁵⁴ M. Pathak,⁸⁰ B. Patricelli,^{40, 18}

- A. S. Patron,² S. Patrone,^{95, 48} S. Paul,⁵⁷ E. Payne,⁵ M. Pedraza,¹ M. Pegoraro,⁷⁵ A. Pele,⁶ F. E. Peña Arellano,¹⁹⁰ S. Penn,²⁶² A. Perego,^{88, 89} A. Pereira,²⁴ T. Pereira,²⁶³ C. J. Perez,⁶⁴ C. Périgois,²⁸ C. C. Perkins,⁶⁹ A. Perreca,^{88, 89} S. Perriès,¹³⁴ J. Petermann,¹²² D. Petterson,¹ H. P. Pfeiffer,¹⁰² K. A. Pham,⁶⁰ K. S. Phukon,^{50, 240} O. J. Piccinni,⁴⁸ M. Pichot,⁹² M. Piendibene,^{71, 18} F. Piergiovanni,^{46, 47} L. Pierini,^{95, 48} V. Pierro,^{79, 94} G. Pillant,⁴⁰ M. Pillas,³⁹ F. Pilo,¹⁸ L. Pinard,¹⁵⁵ I. M. Pinto,^{79, 94, 264} M. Pinto,⁴⁰ K. Piotrkowski,⁴⁹ M. Pirello,⁶⁴ M. D. Pitkin,²⁶⁵ E. Placidi,^{95, 48} L. Planas,¹⁴² W. Plastino,^{243, 244} C. Pluchar,¹³⁸ R. Poggiani,^{71, 18} E. Polini,²⁸ D. Y. T. Pong,¹⁰⁶ S. Ponrathnam,¹¹ P. Popolizio,⁴⁰ E. K. Porter,³⁴ R. Poulton,⁴⁰ J. Powell,¹⁴⁰ M. Pracchia,²⁸ T. Pradier,¹⁶⁰ A. K. Prajapati,⁷⁷ K. Prasai,⁷⁰ R. Prasanna,²⁰⁵ G. Pratten,¹⁴ M. Principe,^{79, 264, 94} G. A. Prodi,^{266, 89} L. Prokhorov,¹⁴ P. Proposito,^{117, 118} L. Prudenzi,¹⁰² A. Puecher,^{50, 111} M. Punturo,⁷² F. Puosi,^{18, 71} P. Puppo,⁴⁸ M. Pürner,¹⁰² H. Qi,¹⁷ V. Quetschke,¹⁴⁸ R. Quitzow-James,⁸⁶ F. J. Raab,⁶⁴ G. Raaijmakers,^{85, 50} H. Radkins,⁶⁴ N. Radulesco,⁹² P. Raffai,¹⁵¹ S. X. Rail,²³³ S. Raja,⁸⁴ C. Rajan,⁸⁴ K. E. Ramirez,⁶ T. D. Ramirez,³⁸ A. Ramos-Buades,¹⁰² J. Rana,¹⁴⁶ P. Rapagnani,^{95, 48} U. D. Rapol,²⁶⁷ A. Ray,⁷ V. Raymond,¹⁷ N. Raza,¹⁷⁸ M. Razzano,^{71, 18} J. Read,³⁸ L. A. Rees,¹⁸⁸ T. Regimbau,²⁸ L. Rei,⁸² S. Reid,³⁰ S. W. Reid,⁵⁴ D. H. Reitze,^{1, 69} P. Relton,¹⁷ A. Renzini,¹ P. Rettengo,^{268, 22} M. Rezac,³⁸ F. Ricci,^{95, 48} D. Richards,¹³⁹ J. W. Richardson,¹ L. Richardson,¹⁸³ G. Riemenschneider,^{268, 22} K. Riles,¹⁸² S. Rinaldi,^{18, 71} K. Rink,¹⁷⁸ M. Rizzo,¹⁵ N. A. Robertson,^{1, 66} R. Robie,¹ F. Robinet,³⁹ A. Rocchi,¹¹⁸ S. Rodriguez,³⁸ L. Rolland,²⁸ J. G. Rollins,¹ M. Romanelli,⁹⁶ R. Romano,^{3, 4} C. L. Romel,⁶⁴ A. Romero-Rodríguez,²¹⁵ I. M. Romero-Shaw,⁵ J. H. Romie,⁶ S. Ronchini,^{29, 98} L. Rosa,^{4, 23} C. A. Rose,⁷ D. Rosińska,¹⁰⁰ M. P. Ross,²⁴² S. Rowan,⁶⁶ S. J. Rowlinson,¹⁴ S. Roy,¹¹¹ Santosh Roy,¹¹ Soumen Roy,²⁶⁹ D. Rozza,^{115, 116} P. Ruggi,⁴⁰ K. Ryan,⁶⁴ S. Sachdev,¹⁴⁶ T. Sadecki,⁶⁴ J. Sadiq,¹⁰⁵ N. Sago,²⁷⁰ S. Saito,²¹ Y. Saito,¹⁹⁰ K. Sakai,²⁷¹ Y. Sakai,¹⁹⁵ M. Sakellariadou,⁵¹ Y. Sakuno,¹²⁵ O. S. Salafia,^{63, 62, 61} L. Salconi,⁴⁰ M. Saleem,⁶⁰ F. Salemi,^{88, 89} A. Samajdar,^{50, 111} E. J. Sanchez,¹ J. H. Sanchez,³⁸ L. E. Sanchez,¹ N. Sanchis-Gual,²⁷² J. R. Sanders,²⁷³ A. Sanuy,²⁷ T. R. Saravanan,¹¹ N. Sarin,⁵ B. Sassolas,¹⁵⁵ H. Satari,⁸³ S. Sato,²⁷⁴ T. Sato,¹⁷³ O. Sauter,⁶⁹ R. L. Savage,⁶⁴ T. Sawada,²⁰² D. Sawant,⁹⁷ H. L. Sawant,¹¹ S. Sayah,¹⁵⁵ D. Schaetzl,¹ M. Scheel,¹³⁰ J. Scheuer,¹⁵ M. Schiowski,⁸⁰ P. Schmidt,¹⁴ S. Schmidt,¹¹¹ R. Schnabel,¹²² M. Schneewind,^{9, 10} R. M. S. Schofield,⁵⁷ A. Schönbeck,¹²² B. W. Schulte,^{9, 10} B. F. Schutz,^{17, 9, 10} E. Schwartz,¹⁷ J. Scott,⁶⁶ S. M. Scott,⁸ M. Seglar-Arroyo,²⁸ T. Sekiguchi,²⁶ Y. Sekiguchi,²⁷⁵ D. Sellers,⁶ A. S. Sengupta,²⁶⁹ D. Sentenac,⁴⁰ E. G. Seo,¹⁰⁶ V. Sequino,^{23, 4} A. Sergeev,²¹⁸ Y. Setyawati,¹¹¹ T. Shaffer,⁶⁴ M. S. Shahriar,¹⁵ B. Shams,¹⁶⁹ L. Shao,¹⁹⁹ A. Sharma,^{29, 98} P. Sharma,⁸⁴ P. Shawhan,¹⁰¹ N. S. Shcheblanov,²³⁷ S. Shibagaki,¹²⁵ M. Shikauchi,¹¹² R. Shimizu,²¹ T. Shimoda,²⁵ K. Shimode,¹⁹⁰ H. Shinkai,²⁷⁶ T. Shishido,⁴⁵ A. Shoda,²⁰ D. H. Shoemaker,⁶⁷ D. M. Shoemaker,¹⁶⁵ S. ShyamSundar,⁸⁴ M. Sieniawska,¹⁰⁰ D. Sigg,⁶⁴ L. P. Singer,¹⁰⁹ D. Singh,¹⁴⁶ N. Singh,¹⁰⁰ A. Singha,^{152, 50} A. M. Sintès,¹⁴² V. Sipala,^{115, 116} V. Skliris,¹⁷ B. J. J. Slagmolen,⁸ T. J. Slaven-Blair,⁸³ J. Smetana,¹⁴ J. R. Smith,³⁸ R. J. E. Smith,⁵ J. Soldateschi,^{277, 278, 47} S. N. Somala,²⁷⁹ K. Somiya,²¹⁶ E. J. Son,²²³ K. Soni,¹¹ S. Soni,² V. Sordini,¹³⁴ F. Sorrentino,⁸² N. Sorrentino,^{71, 18} H. Sotani,²⁸⁰ R. Soulard,⁹² T. Souradeep,^{267, 11} E. Sowell,¹⁴⁵ V. Spagnuolo,^{152, 50} A. P. Spencer,⁶⁶ M. Spera,^{74, 75} R. Srinivasan,⁹² A. K. Srivastava,⁷⁷ V. Srivastava,⁵⁸ K. Staats,¹⁵ C. Stachie,⁹² D. A. Steer,³⁴ J. Steinlechner,^{152, 50} S. Steinlechner,^{152, 50} D. J. Stops,¹⁴ M. Stover,¹⁷⁰ K. A. Strain,⁶⁶ L. C. Strang,¹¹⁴ G. Stratta,^{281, 47} A. Strunk,⁶⁴ R. Sturani,²⁶³ A. L. Stuver,¹²⁰ S. Sudhagar,¹¹ V. Sudhir,⁶⁷ R. Sugimoto,^{282, 204} H. G. Suh,⁷ T. Z. Summerscales,²⁸³ H. Sun,⁸³ L. Sun,⁸ S. Sunil,⁷⁷ A. Sur,⁷⁸ J. Suresh,^{112, 35} P. J. Sutton,¹⁷ Takamasa Suzuki,¹⁷³ Toshikazu Suzuki,³⁵ B. L. Swinkels,⁵⁰ M. J. Szczepańczyk,⁶⁹ P. Szewczyk,¹⁰⁰ M. Tacca,⁵⁰ H. Tagoshi,³⁵ S. C. Tait,⁶⁶ H. Takahashi,²⁸⁴ R. Takahashi,²⁰ A. Takamori,³⁷ S. Takano,²⁵ H. Takeda,²⁵ M. Takeda,²⁰² C. J. Talbot,³⁰ C. Talbot,¹ H. Tanaka,²⁸⁵ Kazuyuki Tanaka,²⁰² Kenta Tanaka,²⁸⁵ Taiki Tanaka,³⁵ Takahiro Tanaka,²⁷⁰ A. J. Tanasijczuk,⁴⁹ S. Tanioka,^{20, 45} D. B. Tanner,⁶⁹ D. Tao,¹ L. Tao,⁶⁹ E. N. Tapia San Martín,^{50, 20} C. Taranto,¹¹⁷ J. D. Tasson,¹⁹¹ S. Telada,²⁸⁶ R. Tenorio,¹⁴² J. E. Terhune,¹²⁰ L. Terkowski,¹²² M. P. Thirugnanasambandam,¹¹ M. Thomas,⁶ P. Thomas,⁶⁴ J. E. Thompson,¹⁷ S. R. Thondapu,⁸⁴ K. A. Thorne,⁶ E. Thrane,⁵ Shubhanshu Tiwari,¹⁵⁸ Srishti Tiwari,¹¹ V. Tiwari,¹⁷ A. M. Toivonen,⁶⁰ K. Toland,⁶⁶ A. E. Tolley,¹⁵³ T. Tomaru,²⁰ Y. Tomigami,²⁰² T. Tomura,¹⁹⁰ M. Tonelli,^{71, 18} A. Torres-Forné,¹²¹ C. I. Torrie,¹ I. Tosta e Melo,^{115, 116} D. Töyrä,⁸ A. Trapananti,^{247, 72} F. Travasso,^{72, 247} G. Traylor,⁶ M. Trevor,¹⁰¹ M. C. Tringali,⁴⁰ A. Tripathi,¹⁸² L. Troiano,^{287, 94} A. Trovato,³⁴ L. Trozzo,^{4, 190} R. J. Trudeau,¹ D. S. Tsai,¹²⁴ D. Tsai,¹²⁴ K. W. Tsang,^{50, 288, 111} T. Tsang,²⁸⁹ J-S. Tsao,¹⁹⁶ M. Tse,⁶⁷ R. Tso,¹³⁰ K. Tsubono,²⁵ S. Tsuchida,²⁰² L. Tsukada,¹¹² D. Tsuna,¹¹² T. Tsutsui,¹¹² T. Tsuzuki,²¹ K. Turbang,^{290, 207} M. Turconi,⁹² D. Tuyenbayev,²⁰² A. S. Ubhi,¹⁴ N. Uchikata,³⁵ T. Uchiyama,¹⁹⁰ R. P. Udall,¹ A. Ueda,¹⁸⁵ T. Uehara,^{291, 292} K. Ueno,¹¹² G. Ueshima,²⁹³ C. S. Unnikrishnan,¹⁷⁹ F. Uraguchi,²¹ A. L. Urban,² T. Ushiba,¹⁹⁰ A. Utina,^{152, 50} H. Vahlbruch,^{9, 10} G. Vajente,¹ A. Vajpeyi,⁵ G. Valdes,¹⁸³ M. Valentini,^{88, 89} V. Valsan,⁷ N. van Bakel,⁵⁰ M. van Beuzekom,⁵⁰ J. F. J. van den Brand,^{152, 294, 50} C. Van Den Broeck,^{111, 50}

D. C. Vander-Hyde,⁵⁸ L. van der Schaaf,⁵⁰ J. V. van Heijningen,⁴⁹ J. Vanosky,¹ M. H. P. M. van Putten,²⁹⁵ N. van Remortel,²⁰⁷ M. Vardaro,^{240,50} A. F. Vargas,¹¹⁴ V. Varma,¹⁷⁷ M. Vasúth,⁶⁸ A. Vecchio,¹⁴ G. Vedovato,⁷⁵ J. Veitch,⁶⁶ P. J. Veitch,⁸⁰ J. Venneberg,^{9,10} G. Venugopalan,¹ D. Verkindt,²⁸ P. Verma,²³⁰ Y. Verma,⁸⁴ D. Veske,⁴³ F. Vetrano,⁴⁶ A. Viceré,^{46,47} S. Vidyant,⁵⁸ A. D. Viets,²⁴⁶ A. Vijaykumar,¹⁹ V. Villa-Ortega,¹⁰⁵ J.-Y. Vinet,⁹² A. Virtuoso,^{186,32} S. Vitale,⁶⁷ T. Vo,⁵⁸ H. Vocca,^{73,72} E. R. G. von Reis,⁶⁴ J. S. A. von Wrangel,^{9,10} C. Vorvick,⁶⁴ S. P. Vyatchanin,⁸⁷ L. E. Wade,¹⁷⁰ M. Wade,¹⁷⁰ K. J. Wagner,¹²³ R. C. Walet,⁵⁰ M. Walker,⁵⁴ G. S. Wallace,³⁰ L. Wallace,¹ S. Walsh,⁷ J. Wang,¹⁷⁴ J. Z. Wang,¹⁸² W. H. Wang,¹⁴⁸ R. L. Ward,⁸ J. Warner,⁶⁴ M. Was,²⁸ T. Washimi,²⁰ N. Y. Washington,¹ J. Watchi,¹⁴³ B. Weaver,⁶⁴ S. A. Webster,⁶⁶ M. Weinert,^{9,10} A. J. Weinstein,¹ R. Weiss,⁶⁷ C. M. Weller,²⁴² F. Wellmann,^{9,10} L. Wen,⁸³ P. Weßels,^{9,10} K. Wette,⁸ J. T. Whelan,¹²³ D. D. White,³⁸ B. F. Whiting,⁶⁹ C. Whittle,⁶⁷ D. Wilken,^{9,10} D. Williams,⁶⁶ M. J. Williams,⁶⁶ A. R. Williamson,¹⁵³ J. L. Willis,¹ B. Willke,^{9,10} D. J. Wilson,¹³⁸ W. Winkler,^{9,10} C. C. Wipf,¹ T. Wlodarczyk,¹⁰² G. Woan,⁶⁶ J. Woehler,^{9,10} J. K. Wofford,¹²³ I. C. F. Wong,¹⁰⁶ C. Wu,¹³¹ D. S. Wu,^{9,10} H. Wu,¹³¹ S. Wu,¹³¹ D. M. Wysocki,⁷ L. Xiao,¹ W.-R. Xu,¹⁹⁶ T. Yamada,²⁸⁵ H. Yamamoto,¹ Kazuhiro Yamamoto,¹⁸⁹ Kohei Yamamoto,²⁸⁵ T. Yamamoto,¹⁹⁰ K. Yamashita,²⁰¹ R. Yamazaki,¹⁹⁸ F. W. Yang,¹⁶⁹ L. Yang,¹⁶³ Y. Yang,²⁹⁶ Yang Yang,⁶⁹ Z. Yang,⁶⁰ M. J. Yap,⁸ D. W. Yeeles,¹⁷ A. B. Yelikar,¹²³ M. Ying,¹²⁴ K. Yokogawa,²⁰¹ J. Yokoyama,^{26,25} T. Yokozawa,¹⁹⁰ J. Yoo,¹⁷⁷ T. Yoshioka,²⁰¹ Hang Yu,¹³⁰ Haocun Yu,⁶⁷ H. Yuzurihara,³⁵ A. Zadrożny,²³⁰ M. Zanolin,³³ S. Zeidler,²⁹⁷ T. Zelenova,⁴⁰ J.-P. Zendri,⁷⁵ M. Zevin,¹⁵⁹ M. Zhan,¹⁷⁴ H. Zhang,¹⁹⁶ J. Zhang,⁸³ L. Zhang,¹ T. Zhang,¹⁴ Y. Zhang,¹⁸³ C. Zhao,⁸³ G. Zhao,¹⁴³ Y. Zhao,²⁰ Yue Zhao,¹⁶⁹ R. Zhou,¹⁹² Z. Zhou,¹⁵ X. J. Zhu,⁵ Z.-H. Zhu,¹¹³ A. B. Zimmerman,¹⁶⁵ M. E. Zucker,^{1,67} and J. Zweizig¹

¹LIGO Laboratory, California Institute of Technology, Pasadena, CA 91125, USA

²Louisiana State University, Baton Rouge, LA 70803, USA

³Dipartimento di Farmacia, Università di Salerno, I-84084 Fisciano, Salerno, Italy

⁴INFN, Sezione di Napoli, Complesso Universitario di Monte S. Angelo, I-80126 Napoli, Italy

⁵OzGrav, School of Physics & Astronomy, Monash University, Clayton 3800, Victoria, Australia

⁶LIGO Livingston Observatory, Livingston, LA 70754, USA

⁷University of Wisconsin-Milwaukee, Milwaukee, WI 53201, USA

⁸OzGrav, Australian National University, Canberra, Australian Capital Territory 0200, Australia

⁹Max Planck Institute for Gravitational Physics (Albert Einstein Institute), D-30167 Hannover, Germany

¹⁰Leibniz Universität Hannover, D-30167 Hannover, Germany

¹¹Inter-University Centre for Astronomy and Astrophysics, Pune 411007, India

¹²University of Cambridge, Cambridge CB2 1TN, United Kingdom

¹³Theoretisch-Physikalisches Institut, Friedrich-Schiller-Universität Jena, D-07743 Jena, Germany

¹⁴University of Birmingham, Birmingham B15 2TT, United Kingdom

¹⁵Center for Interdisciplinary Exploration & Research in Astrophysics (CIERA), Northwestern University, Evanston, IL 60208, USA

¹⁶Instituto Nacional de Pesquisas Espaciais, 12227-010 São José dos Campos, São Paulo, Brazil

¹⁷Gravity Exploration Institute, Cardiff University, Cardiff CF24 3AA, United Kingdom

¹⁸INFN, Sezione di Pisa, I-56127 Pisa, Italy

¹⁹International Centre for Theoretical Sciences, Tata Institute of Fundamental Research, Bengaluru 560089, India

²⁰Gravitational Wave Science Project, National Astronomical

Observatory of Japan (NAOJ), Mitaka City, Tokyo 181-8588, Japan

²¹Advanced Technology Center, National Astronomical Observatory of Japan (NAOJ), Mitaka City, Tokyo 181-8588, Japan

²²INFN Sezione di Torino, I-10125 Torino, Italy

²³Università di Napoli “Federico II”, Complesso Universitario di Monte S. Angelo, I-80126 Napoli, Italy

²⁴Université de Lyon, Université Claude Bernard Lyon 1,

CNRS, Institut Lumière Matière, F-69622 Villeurbanne, France

²⁵Department of Physics, The University of Tokyo, Bunkyo-ku, Tokyo 113-0033, Japan

²⁶Research Center for the Early Universe (RESCEU),

The University of Tokyo, Bunkyo-ku, Tokyo 113-0033, Japan

²⁷Institut de Ciències del Cosmos (ICCUB), Universitat de Barcelona,

C/ Martí i Franquès 1, Barcelona, 08028, Spain

²⁸Laboratoire d’Annecy de Physique des Particules (LAPP), Univ. Grenoble Alpes,

Université Savoie Mont Blanc, CNRS/IN2P3, F-74941 Annecy, France

²⁹Gran Sasso Science Institute (GSSI), I-67100 L’Aquila, Italy

³⁰SUPA, University of Strathclyde, Glasgow G1 1XQ, United Kingdom

³¹Dipartimento di Scienze Matematiche, Informatiche e Fisiche, Università di Udine, I-33100 Udine, Italy

³²INFN, Sezione di Trieste, I-34127 Trieste, Italy

³³Embry-Riddle Aeronautical University, Prescott, AZ 86301, USA

³⁴Université de Paris, CNRS, Astroparticule et Cosmologie, F-75006 Paris, France

- ³⁵ *Institute for Cosmic Ray Research (ICRR), KAGRA Observatory,
The University of Tokyo, Kashiwa City, Chiba 277-8582, Japan*
- ³⁶ *Accelerator Laboratory, High Energy Accelerator Research Organization (KEK), Tsukuba City, Ibaraki 305-0801, Japan*
- ³⁷ *Earthquake Research Institute, The University of Tokyo, Bunkyo-ku, Tokyo 113-0032, Japan*
- ³⁸ *California State University Fullerton, Fullerton, CA 92831, USA*
- ³⁹ *Université Paris-Saclay, CNRS/IN2P3, IJCLab, 91405 Orsay, France*
- ⁴⁰ *European Gravitational Observatory (EGO), I-56021 Cascina, Pisa, Italy*
- ⁴¹ *Chennai Mathematical Institute, Chennai 603103, India*
- ⁴² *Department of Mathematics and Physics, Gravitational Wave Science Project,
Hirosaki University, Hirosaki City, Aomori 036-8561, Japan*
- ⁴³ *Columbia University, New York, NY 10027, USA*
- ⁴⁴ *Kamioka Branch, National Astronomical Observatory of Japan (NAOJ), Kamioka-cho, Hida City, Gifu 506-1205, Japan*
- ⁴⁵ *The Graduate University for Advanced Studies (SOKENDAI), Mitaka City, Tokyo 181-8588, Japan*
- ⁴⁶ *Università degli Studi di Urbino “Carlo Bo”, I-61029 Urbino, Italy*
- ⁴⁷ *INFN, Sezione di Firenze, I-50019 Sesto Fiorentino, Firenze, Italy*
- ⁴⁸ *INFN, Sezione di Roma, I-00185 Roma, Italy*
- ⁴⁹ *Université catholique de Louvain, B-1348 Louvain-la-Neuve, Belgium*
- ⁵⁰ *Nikhef, Science Park 105, 1098 XG Amsterdam, Netherlands*
- ⁵¹ *King’s College London, University of London, London WC2R 2LS, United Kingdom*
- ⁵² *Korea Institute of Science and Technology Information (KISTI), Yuseong-gu, Daejeon 34141, Korea*
- ⁵³ *National Institute for Mathematical Sciences, Yuseong-gu, Daejeon 34047, Korea*
- ⁵⁴ *Christopher Newport University, Newport News, VA 23606, USA*
- ⁵⁵ *International College, Osaka University, Toyonaka City, Osaka 560-0043, Japan*
- ⁵⁶ *School of High Energy Accelerator Science, The Graduate University for
Advanced Studies (SOKENDAI), Tsukuba City, Ibaraki 305-0801, Japan*
- ⁵⁷ *University of Oregon, Eugene, OR 97403, USA*
- ⁵⁸ *Syracuse University, Syracuse, NY 13244, USA*
- ⁵⁹ *Université de Liège, B-4000 Liège, Belgium*
- ⁶⁰ *University of Minnesota, Minneapolis, MN 55455, USA*
- ⁶¹ *Università degli Studi di Milano-Bicocca, I-20126 Milano, Italy*
- ⁶² *INFN, Sezione di Milano-Bicocca, I-20126 Milano, Italy*
- ⁶³ *INAF, Osservatorio Astronomico di Brera sede di Merate, I-23807 Merate, Lecco, Italy*
- ⁶⁴ *LIGO Hanford Observatory, Richland, WA 99352, USA*
- ⁶⁵ *Dipartimento di Medicina, Chirurgia e Odontoiatria “Scuola Medica Salernitana”,
Università di Salerno, I-84081 Baronissi, Salerno, Italy*
- ⁶⁶ *SUPA, University of Glasgow, Glasgow G12 8QQ, United Kingdom*
- ⁶⁷ *LIGO Laboratory, Massachusetts Institute of Technology, Cambridge, MA 02139, USA*
- ⁶⁸ *Wigner RCP, RMKI, H-1121 Budapest, Konkoly Thege Miklós út 29-33, Hungary*
- ⁶⁹ *University of Florida, Gainesville, FL 32611, USA*
- ⁷⁰ *Stanford University, Stanford, CA 94305, USA*
- ⁷¹ *Università di Pisa, I-56127 Pisa, Italy*
- ⁷² *INFN, Sezione di Perugia, I-06123 Perugia, Italy*
- ⁷³ *Università di Perugia, I-06123 Perugia, Italy*
- ⁷⁴ *Università di Padova, Dipartimento di Fisica e Astronomia, I-35131 Padova, Italy*
- ⁷⁵ *INFN, Sezione di Padova, I-35131 Padova, Italy*
- ⁷⁶ *Montana State University, Bozeman, MT 59717, USA*
- ⁷⁷ *Institute for Plasma Research, Bhat, Gandhinagar 382428, India*
- ⁷⁸ *Nicolaus Copernicus Astronomical Center, Polish Academy of Sciences, 00-716, Warsaw, Poland*
- ⁷⁹ *Dipartimento di Ingegneria, Università del Sannio, I-82100 Benevento, Italy*
- ⁸⁰ *OzGrav, University of Adelaide, Adelaide, South Australia 5005, Australia*
- ⁸¹ *California State University, Los Angeles, 5151 State University Dr, Los Angeles, CA 90032, USA*
- ⁸² *INFN, Sezione di Genova, I-16146 Genova, Italy*
- ⁸³ *OzGrav, University of Western Australia, Crawley, Western Australia 6009, Australia*
- ⁸⁴ *RRCAT, Indore, Madhya Pradesh 452013, India*
- ⁸⁵ *GRAPPA, Anton Pannekoek Institute for Astronomy and Institute for High-Energy Physics,
University of Amsterdam, Science Park 904, 1098 XH Amsterdam, Netherlands*
- ⁸⁶ *Missouri University of Science and Technology, Rolla, MO 65409, USA*
- ⁸⁷ *Faculty of Physics, Lomonosov Moscow State University, Moscow 119991, Russia*
- ⁸⁸ *Università di Trento, Dipartimento di Fisica, I-38123 Povo, Trento, Italy*
- ⁸⁹ *INFN, Trento Institute for Fundamental Physics and Applications, I-38123 Povo, Trento, Italy*
- ⁹⁰ *SUPA, University of the West of Scotland, Paisley PA1 2BE, United Kingdom*
- ⁹¹ *Bar-Ilan University, Ramat Gan, 5290002, Israel*
- ⁹² *Artemis, Université Côte d’Azur, Observatoire de la Côte d’Azur, CNRS, F-06304 Nice, France*
- ⁹³ *Dipartimento di Fisica “E.R. Caianiello”, Università di Salerno, I-84084 Fisciano, Salerno, Italy*

- ⁹⁴ INFN, Sezione di Napoli, Gruppo Collegato di Salerno,
Complesso Universitario di Monte S. Angelo, I-80126 Napoli, Italy
- ⁹⁵ Università di Roma “La Sapienza”, I-00185 Roma, Italy
- ⁹⁶ Univ Rennes, CNRS, Institut FOTON - UMR6082, F-3500 Rennes, France
- ⁹⁷ Indian Institute of Technology Bombay, Powai, Mumbai 400 076, India
- ⁹⁸ INFN, Laboratori Nazionali del Gran Sasso, I-67100 Assergi, Italy
- ⁹⁹ Laboratoire Kastler Brossel, Sorbonne Université, CNRS,
ENS-Université PSL, Collège de France, F-75005 Paris, France
- ¹⁰⁰ Astronomical Observatory Warsaw University, 00-478 Warsaw, Poland
- ¹⁰¹ University of Maryland, College Park, MD 20742, USA
- ¹⁰² Max Planck Institute for Gravitational Physics (Albert Einstein Institute), D-14476 Potsdam, Germany
- ¹⁰³ L2IT, Laboratoire des 2 Infinis - Toulouse, Université de Toulouse,
CNRS/IN2P3, UPS, F-31062 Toulouse Cedex 9, France
- ¹⁰⁴ School of Physics, Georgia Institute of Technology, Atlanta, GA 30332, USA
- ¹⁰⁵ IGFAE, Campus Sur, Universidad de Santiago de Compostela, 15782 Spain
- ¹⁰⁶ The Chinese University of Hong Kong, Shatin, NT, Hong Kong
- ¹⁰⁷ Stony Brook University, Stony Brook, NY 11794, USA
- ¹⁰⁸ Center for Computational Astrophysics, Flatiron Institute, New York, NY 10010, USA
- ¹⁰⁹ NASA Goddard Space Flight Center, Greenbelt, MD 20771, USA
- ¹¹⁰ Dipartimento di Fisica, Università degli Studi di Genova, I-16146 Genova, Italy
- ¹¹¹ Institute for Gravitational and Subatomic Physics (GRASP),
Utrecht University, Princetonplein 1, 3584 CC Utrecht, Netherlands
- ¹¹² RESCEU, University of Tokyo, Tokyo, 113-0033, Japan.
- ¹¹³ Department of Astronomy, Beijing Normal University, Beijing 100875, China
- ¹¹⁴ OzGrav, University of Melbourne, Parkville, Victoria 3010, Australia
- ¹¹⁵ Università degli Studi di Sassari, I-07100 Sassari, Italy
- ¹¹⁶ INFN, Laboratori Nazionali del Sud, I-95125 Catania, Italy
- ¹¹⁷ Università di Roma Tor Vergata, I-00133 Roma, Italy
- ¹¹⁸ INFN, Sezione di Roma Tor Vergata, I-00133 Roma, Italy
- ¹¹⁹ University of Sannio at Benevento, I-82100 Benevento,
Italy and INFN, Sezione di Napoli, I-80100 Napoli, Italy
- ¹²⁰ Villanova University, 800 Lancaster Ave, Villanova, PA 19085, USA
- ¹²¹ Departamento de Astronomía y Astrofísica, Universitat de València, E-46100 Burjassot, València, Spain
- ¹²² Universität Hamburg, D-22761 Hamburg, Germany
- ¹²³ Rochester Institute of Technology, Rochester, NY 14623, USA
- ¹²⁴ National Tsing Hua University, Hsinchu City, 30013 Taiwan, Republic of China
- ¹²⁵ Department of Applied Physics, Fukuoka University, Jonan, Fukuoka City, Fukuoka 814-0180, Japan
- ¹²⁶ OzGrav, Charles Sturt University, Wagga Wagga, New South Wales 2678, Australia
- ¹²⁷ Department of Physics, Tamkang University, Danshui Dist., New Taipei City 25137, Taiwan
- ¹²⁸ Department of Physics and Institute of Astronomy,
National Tsing Hua University, Hsinchu 30013, Taiwan
- ¹²⁹ Department of Physics, Center for High Energy and High Field Physics,
National Central University, Zhongli District, Taoyuan City 32001, Taiwan
- ¹³⁰ CaRT, California Institute of Technology, Pasadena, CA 91125, USA
- ¹³¹ Department of Physics, National Tsing Hua University, Hsinchu 30013, Taiwan
- ¹³² Dipartimento di Ingegneria Industriale (DIIN),
Università di Salerno, I-84084 Fisciano, Salerno, Italy
- ¹³³ Institute of Physics, Academia Sinica, Nankang, Taipei 11529, Taiwan
- ¹³⁴ Université Lyon, Université Claude Bernard Lyon 1, CNRS,
IP2I Lyon / IN2P3, UMR 5822, F-69622 Villeurbanne, France
- ¹³⁵ Seoul National University, Seoul 08826, South Korea
- ¹³⁶ Pusan National University, Busan 46241, South Korea
- ¹³⁷ INAF, Osservatorio Astronomico di Padova, I-35122 Padova, Italy
- ¹³⁸ University of Arizona, Tucson, AZ 85721, USA
- ¹³⁹ Rutherford Appleton Laboratory, Didcot OX11 0DE, United Kingdom
- ¹⁴⁰ OzGrav, Swinburne University of Technology, Hawthorn VIC 3122, Australia
- ¹⁴¹ Université libre de Bruxelles, Avenue Franklin Roosevelt 50 - 1050 Bruxelles, Belgium
- ¹⁴² Universitat de les Illes Balears, IAC3—IEEC, E-07122 Palma de Mallorca, Spain
- ¹⁴³ Université Libre de Bruxelles, Brussels 1050, Belgium
- ¹⁴⁴ Departamento de Matemáticas, Universitat de València, E-46100 Burjassot, València, Spain
- ¹⁴⁵ Texas Tech University, Lubbock, TX 79409, USA
- ¹⁴⁶ The Pennsylvania State University, University Park, PA 16802, USA
- ¹⁴⁷ University of Rhode Island, Kingston, RI 02881, USA
- ¹⁴⁸ The University of Texas Rio Grande Valley, Brownsville, TX 78520, USA

- ¹⁴⁹ *Bellevue College, Bellevue, WA 98007, USA*
- ¹⁵⁰ *Scuola Normale Superiore, Piazza dei Cavalieri, 7 - 56126 Pisa, Italy*
- ¹⁵¹ *MTA-ELTE Astrophysics Research Group, Institute of Physics, Eötvös University, Budapest 1117, Hungary*
- ¹⁵² *Maastricht University, P.O. Box 616, 6200 MD Maastricht, Netherlands*
- ¹⁵³ *University of Portsmouth, Portsmouth, PO1 3FX, United Kingdom*
- ¹⁵⁴ *The University of Sheffield, Sheffield S10 2TN, United Kingdom*
- ¹⁵⁵ *Université Lyon, Université Claude Bernard Lyon 1,
CNRS, Laboratoire des Matériaux Avancés (LMA),
IP2I Lyon / IN2P3, UMR 5822, F-69622 Villeurbanne, France*
- ¹⁵⁶ *Dipartimento di Scienze Matematiche, Fisiche e Informatiche, Università di Parma, I-43124 Parma, Italy*
- ¹⁵⁷ *INFN, Sezione di Milano Bicocca, Gruppo Collegato di Parma, I-43124 Parma, Italy*
- ¹⁵⁸ *Physik-Institut, University of Zurich, Winterthurerstrasse 190, 8057 Zurich, Switzerland*
- ¹⁵⁹ *University of Chicago, Chicago, IL 60637, USA*
- ¹⁶⁰ *Université de Strasbourg, CNRS, IPHC UMR 7178, F-67000 Strasbourg, France*
- ¹⁶¹ *West Virginia University, Morgantown, WV 26506, USA*
- ¹⁶² *Montclair State University, Montclair, NJ 07043, USA*
- ¹⁶³ *Colorado State University, Fort Collins, CO 80523, USA*
- ¹⁶⁴ *Institute for Nuclear Research, Hungarian Academy of Sciences, Bem tér 18/c, H-4026 Debrecen, Hungary*
- ¹⁶⁵ *Department of Physics, University of Texas, Austin, TX 78712, USA*
- ¹⁶⁶ *CNR-SPIN, c/o Università di Salerno, I-84084 Fisciano, Salerno, Italy*
- ¹⁶⁷ *Scuola di Ingegneria, Università della Basilicata, I-85100 Potenza, Italy*
- ¹⁶⁸ *Observatori Astronòmic, Universitat de València, E-46980 Paterna, València, Spain*
- ¹⁶⁹ *The University of Utah, Salt Lake City, UT 84112, USA*
- ¹⁷⁰ *Kenyon College, Gambier, OH 43022, USA*
- ¹⁷¹ *Vrije Universiteit Amsterdam, 1081 HV, Amsterdam, Netherlands*
- ¹⁷² *Department of Astronomy, The University of Tokyo, Mitaka City, Tokyo 181-8588, Japan*
- ¹⁷³ *Faculty of Engineering, Niigata University, Nishi-ku, Niigata City, Niigata 950-2181, Japan*
- ¹⁷⁴ *State Key Laboratory of Magnetic Resonance and Atomic and Molecular Physics,
Innovation Academy for Precision Measurement Science and Technology (APM),
Chinese Academy of Sciences, Xiao Hong Shan, Wuhan 430071, China*
- ¹⁷⁵ *University of Szeged, Dóm tér 9, Szeged 6720, Hungary*
- ¹⁷⁶ *Universiteit Gent, B-9000 Gent, Belgium*
- ¹⁷⁷ *Cornell University, Ithaca, NY 14850, USA*
- ¹⁷⁸ *University of British Columbia, Vancouver, BC V6T 1Z4, Canada*
- ¹⁷⁹ *Tata Institute of Fundamental Research, Mumbai 400005, India*
- ¹⁸⁰ *INAF, Osservatorio Astronomico di Capodimonte, I-80131 Napoli, Italy*
- ¹⁸¹ *The University of Mississippi, University, MS 38677, USA*
- ¹⁸² *University of Michigan, Ann Arbor, MI 48109, USA*
- ¹⁸³ *Texas A&M University, College Station, TX 77843, USA*
- ¹⁸⁴ *Department of Physics, Ulsan National Institute of Science and Technology (UNIST), Ulsu-gun, Ulsan 44919, Korea*
- ¹⁸⁵ *Applied Research Laboratory, High Energy Accelerator Research Organization (KEK), Tsukuba City, Ibaraki 305-0801, Japan*
- ¹⁸⁶ *Dipartimento di Fisica, Università di Trieste, I-34127 Trieste, Italy*
- ¹⁸⁷ *Shanghai Astronomical Observatory, Chinese Academy of Sciences, Shanghai 200030, China*
- ¹⁸⁸ *American University, Washington, D.C. 20016, USA*
- ¹⁸⁹ *Faculty of Science, University of Toyama, Toyama City, Toyama 930-8555, Japan*
- ¹⁹⁰ *Institute for Cosmic Ray Research (ICRR), KAGRA Observatory,
The University of Tokyo, Kamioka-cho, Hida City, Gifu 506-1205, Japan*
- ¹⁹¹ *Carleton College, Northfield, MN 55057, USA*
- ¹⁹² *University of California, Berkeley, CA 94720, USA*
- ¹⁹³ *Maastricht University, 6200 MD, Maastricht, Netherlands*
- ¹⁹⁴ *College of Industrial Technology, Nihon University, Narashino City, Chiba 275-8575, Japan*
- ¹⁹⁵ *Graduate School of Science and Technology, Niigata University, Nishi-ku, Niigata City, Niigata 950-2181, Japan*
- ¹⁹⁶ *Department of Physics, National Taiwan Normal University, sec. 4, Taipei 116, Taiwan*
- ¹⁹⁷ *Astronomy & Space Science, Chungnam National University, Yuseong-gu, Daejeon 34134, Korea, Korea*
- ¹⁹⁸ *Department of Physics and Mathematics, Aoyama Gakuin University, Sagami-hara City, Kanagawa 252-5258, Japan*
- ¹⁹⁹ *Kavli Institute for Astronomy and Astrophysics,
Peking University, Haidian District, Beijing 100871, China*
- ²⁰⁰ *Yukawa Institute for Theoretical Physics (YITP),
Kyoto University, Sakyo-ku, Kyoto City, Kyoto 606-8502, Japan*
- ²⁰¹ *Graduate School of Science and Engineering, University of Toyama, Toyama City, Toyama 930-8555, Japan*
- ²⁰² *Department of Physics, Graduate School of Science,
Osaka City University, Sumiyoshi-ku, Osaka City, Osaka 558-8585, Japan*
- ²⁰³ *Nambu Yoichiro Institute of Theoretical and Experimental Physics (NITEP),
Osaka City University, Sumiyoshi-ku, Osaka City, Osaka 558-8585, Japan*

- ²⁰⁴ *Institute of Space and Astronautical Science (JAXA),
Chuo-ku, Sagami-hara City, Kanagawa 252-0222, Japan*
- ²⁰⁵ *Directorate of Construction, Services & Estate Management, Mumbai 400094, India*
- ²⁰⁶ *Vanderbilt University, Nashville, TN 37235, USA*
- ²⁰⁷ *Universiteit Antwerpen, Prinsstraat 13, 2000 Antwerpen, Belgium*
- ²⁰⁸ *University of Białystok, 15-424 Białystok, Poland*
- ²⁰⁹ *Department of Physics, Ewha Womans University, Seodaemun-gu, Seoul 03760, Korea*
- ²¹⁰ *National Astronomical Observatories, Chinese Academic of Sciences, Chaoyang District, Beijing, China*
- ²¹¹ *School of Astronomy and Space Science, University of Chinese Academy of Sciences, Chaoyang District, Beijing, China*
- ²¹² *University of Southampton, Southampton SO17 1BJ, United Kingdom*
- ²¹³ *Institute for Cosmic Ray Research (ICRR), The University of Tokyo, Kashiwa City, Chiba 277-8582, Japan*
- ²¹⁴ *Chung-Ang University, Seoul 06974, South Korea*
- ²¹⁵ *Institut de Física d'Altes Energies (IFAE), Barcelona Institute
of Science and Technology, and ICREA, E-08193 Barcelona, Spain*
- ²¹⁶ *Graduate School of Science, Tokyo Institute of Technology, Meguro-ku, Tokyo 152-8551, Japan*
- ²¹⁷ *University of Washington Bothell, Bothell, WA 98011, USA*
- ²¹⁸ *Institute of Applied Physics, Nizhny Novgorod, 603950, Russia*
- ²¹⁹ *Ewha Womans University, Seoul 03760, South Korea*
- ²²⁰ *Inje University Gimhae, South Gyeongsang 50834, South Korea*
- ²²¹ *Department of Physics, Myongji University, Yongin 17058, Korea*
- ²²² *Korea Astronomy and Space Science Institute, Daejeon 34055, South Korea*
- ²²³ *National Institute for Mathematical Sciences, Daejeon 34047, South Korea*
- ²²⁴ *Ulsan National Institute of Science and Technology, Ulsan 44919, South Korea*
- ²²⁵ *Department of Physical Science, Hiroshima University,
Higashihiroshima City, Hiroshima 733-0213, Japan*
- ²²⁶ *School of Physics and Astronomy, Cardiff University, Cardiff, CF24 3AA, UK*
- ²²⁷ *Institute of Astronomy, National Tsing Hua University, Hsinchu 30013, Taiwan*
- ²²⁸ *Bard College, 30 Campus Rd, Annandale-On-Hudson, NY 12504, USA*
- ²²⁹ *Institute of Mathematics, Polish Academy of Sciences, 00656 Warsaw, Poland*
- ²³⁰ *National Center for Nuclear Research, 05-400 Świerk-Otwock, Poland*
- ²³¹ *Instituto de Física Teórica, 28049 Madrid, Spain*
- ²³² *Department of Physics, Nagoya University, Chikusa-ku, Nagoya, Aichi 464-8602, Japan*
- ²³³ *Université de Montréal/Polytechnique, Montreal, Quebec H3T 1J4, Canada*
- ²³⁴ *Laboratoire Lagrange, Université Côte d'Azur,
Observatoire Côte d'Azur, CNRS, F-06304 Nice, France*
- ²³⁵ *Department of Physics, Hanyang University, Seoul 04763, Korea*
- ²³⁶ *Sungkyunkwan University, Seoul 03063, South Korea*
- ²³⁷ *NAVIER, École des Ponts, Univ Gustave Eiffel, CNRS, Marne-la-Vallée, France*
- ²³⁸ *Department of Physics, National Cheng Kung University, Tainan City 701, Taiwan*
- ²³⁹ *National Center for High-performance computing, National Applied Research Laboratories,
Hsinchu Science Park, Hsinchu City 30076, Taiwan*
- ²⁴⁰ *Institute for High-Energy Physics, University of Amsterdam,
Science Park 904, 1098 XH Amsterdam, Netherlands*
- ²⁴¹ *NASA Marshall Space Flight Center, Huntsville, AL 35811, USA*
- ²⁴² *University of Washington, Seattle, WA 98195, USA*
- ²⁴³ *Dipartimento di Matematica e Fisica, Università degli Studi Roma Tre, I-00146 Roma, Italy*
- ²⁴⁴ *INFN, Sezione di Roma Tre, I-00146 Roma, Italy*
- ²⁴⁵ *ESPCI, CNRS, F-75005 Paris, France*
- ²⁴⁶ *Concordia University Wisconsin, Mequon, WI 53097, USA*
- ²⁴⁷ *Università di Camerino, Dipartimento di Fisica, I-62032 Camerino, Italy*
- ²⁴⁸ *School of Physics Science and Engineering, Tongji University, Shanghai 200092, China*
- ²⁴⁹ *Southern University and A&M College, Baton Rouge, LA 70813, USA*
- ²⁵⁰ *Centre Scientifique de Monaco, 8 quai Antoine 1er, MC-98000, Monaco*
- ²⁵¹ *Institute for Photon Science and Technology, The University of Tokyo, Bunkyo-ku, Tokyo 113-8656, Japan*
- ²⁵² *Indian Institute of Technology Madras, Chennai 600036, India*
- ²⁵³ *Saha Institute of Nuclear Physics, Bidhannagar, West Bengal 700064, India*
- ²⁵⁴ *The Applied Electromagnetic Research Institute,
National Institute of Information and Communications Technology (NICT), Koganei City, Tokyo 184-8795, Japan*
- ²⁵⁵ *Institut des Hautes Etudes Scientifiques, F-91440 Bures-sur-Yvette, France*
- ²⁵⁶ *Faculty of Law, Ryukoku University, Fushimi-ku, Kyoto City, Kyoto 612-8577, Japan*
- ²⁵⁷ *Indian Institute of Science Education and Research, Kolkata, Mohanpur, West Bengal 741252, India*
- ²⁵⁸ *Department of Astrophysics/IMAPP, Radboud University Nijmegen,
P.O. Box 9010, 6500 GL Nijmegen, Netherlands*
- ²⁵⁹ *Department of Physics, University of Notre Dame, Notre Dame, IN 46556, USA*

- ²⁶⁰ *Consiglio Nazionale delle Ricerche - Istituto dei Sistemi Complessi, Piazzale Aldo Moro 5, I-00185 Roma, Italy*
- ²⁶¹ *Korea Astronomy and Space Science Institute (KASI), Yuseong-gu, Daejeon 34055, Korea*
- ²⁶² *Hobart and William Smith Colleges, Geneva, NY 14456, USA*
- ²⁶³ *International Institute of Physics, Universidade Federal do Rio Grande do Norte, Natal RN 59078-970, Brazil*
- ²⁶⁴ *Museo Storico della Fisica e Centro Studi e Ricerche "Enrico Fermi", I-00184 Roma, Italy*
- ²⁶⁵ *Lancaster University, Lancaster LA1 4YW, United Kingdom*
- ²⁶⁶ *Università di Trento, Dipartimento di Matematica, I-38123 Povo, Trento, Italy*
- ²⁶⁷ *Indian Institute of Science Education and Research, Pune, Maharashtra 411008, India*
- ²⁶⁸ *Dipartimento di Fisica, Università degli Studi di Torino, I-10125 Torino, Italy*
- ²⁶⁹ *Indian Institute of Technology, Palaj, Gandhinagar, Gujarat 382355, India*
- ²⁷⁰ *Department of Physics, Kyoto University, Sakyou-ku, Kyoto City, Kyoto 606-8502, Japan*
- ²⁷¹ *Department of Electronic Control Engineering, National Institute of Technology, Nagaoka College, Nagaoka City, Niigata 940-8532, Japan*
- ²⁷² *Departamento de Matemática da Universidade de Aveiro and Centre for Research and Development in Mathematics and Applications, Campus de Santiago, 3810-183 Aveiro, Portugal*
- ²⁷³ *Marquette University, 11420 W. Clybourn St., Milwaukee, WI 53233, USA*
- ²⁷⁴ *Graduate School of Science and Engineering, Hosei University, Koganei City, Tokyo 184-8584, Japan*
- ²⁷⁵ *Faculty of Science, Toho University, Funabashi City, Chiba 274-8510, Japan*
- ²⁷⁶ *Faculty of Information Science and Technology, Osaka Institute of Technology, Hirakata City, Osaka 573-0196, Japan*
- ²⁷⁷ *Università di Firenze, Sesto Fiorentino I-50019, Italy*
- ²⁷⁸ *INAF, Osservatorio Astrofisico di Arcetri, Largo E. Fermi 5, I-50125 Firenze, Italy*
- ²⁷⁹ *Indian Institute of Technology Hyderabad, Sangareddy, Khandi, Telangana 502285, India*
- ²⁸⁰ *iTHEMS (Interdisciplinary Theoretical and Mathematical Sciences Program), The Institute of Physical and Chemical Research (RIKEN), Wako, Saitama 351-0198, Japan*
- ²⁸¹ *INAF, Osservatorio di Astrofisica e Scienza dello Spazio, I-40129 Bologna, Italy*
- ²⁸² *Department of Space and Astronautical Science, The Graduate University for Advanced Studies (SOKENDAI), Sagami-hara City, Kanagawa 252-5210, Japan*
- ²⁸³ *Andrews University, Berrien Springs, MI 49104, USA*
- ²⁸⁴ *Research Center for Space Science, Advanced Research Laboratories, Tokyo City University, Setagaya, Tokyo 158-0082, Japan*
- ²⁸⁵ *Institute for Cosmic Ray Research (ICRR), Research Center for Cosmic Neutrinos (RCCN), The University of Tokyo, Kashiwa City, Chiba 277-8582, Japan*
- ²⁸⁶ *National Metrology Institute of Japan, National Institute of Advanced Industrial Science and Technology, Tsukuba City, Ibaraki 305-8568, Japan*
- ²⁸⁷ *Dipartimento di Scienze Aziendali - Management and Innovation Systems (DISA-MIS), Università di Salerno, I-84084 Fisciano, Salerno, Italy*
- ²⁸⁸ *Van Swinderen Institute for Particle Physics and Gravity, University of Groningen, Nijenborgh 4, 9747 AG Groningen, Netherlands*
- ²⁸⁹ *Faculty of Science, Department of Physics, The Chinese University of Hong Kong, Shatin, N.T., Hong Kong*
- ²⁹⁰ *Vrije Universiteit Brussel, Boulevard de la Plaine 2, 1050 Ixelles, Belgium*
- ²⁹¹ *Department of Communications Engineering, National Defense Academy of Japan, Yokosuka City, Kanagawa 239-8686, Japan*
- ²⁹² *Department of Physics, University of Florida, Gainesville, FL 32611, USA*
- ²⁹³ *Department of Information and Management Systems Engineering, Nagaoka University of Technology, Nagaoka City, Niigata 940-2188, Japan*
- ²⁹⁴ *Vrije Universiteit Amsterdam, 1081 HV Amsterdam, Netherlands*
- ²⁹⁵ *Department of Physics and Astronomy, Sejong University, Gwangjin-gu, Seoul 143-747, Korea*
- ²⁹⁶ *Department of Electrophysics, National Chiao Tung University, Hsinchu, Taiwan*
- ²⁹⁷ *Department of Physics, Rikkyo University, Toshima-ku, Tokyo 171-8501, Japan*
- (compiled July 30, 2021)

^a Deceased, August 2020.